

# Gradient Estimates of Solutions to the Conductivity Problem with Flatter Insulators

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Dedicated to Prof. Paul H. Rabinowitz with admiration on the occasion of his 80th birthday

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**Abstract.** We study the insulated conductivity problem with inclusions embedded in a bounded domain in  $\mathbb{R}^n$ . When the distance of inclusions, denoted by  $\varepsilon$ , goes to 0, the gradient of solutions may blow up. When two inclusions are strictly convex, it was known that an upper bound of the blow-up rate is of order  $\varepsilon^{-1/2}$  for  $n = 2$ , and is of order  $\varepsilon^{-1/2+\beta}$  for some  $\beta > 0$  when dimension  $n \geq 3$ . In this paper, we generalize the above results for insulators with flatter boundaries near touching points.

**Key Words:** Conductivity problem, harmonic functions, maximum principle, gradient estimates.

**AMS Subject Classifications:** 35B44, 35J25, 35J57, 74B05, 74G70, 78A48

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## 1 Introduction and main results

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  with  $C^2$  boundary, and let  $D_1^*$  and  $D_2^*$  be two open sets whose closure belongs to  $\Omega$ , touching only at the origin with the inner normal vector of  $\partial D_1^*$  pointing in the positive  $x_n$ -direction. Denote  $x = (x', x_n)$ . Translating  $D_1^*$  and  $D_2^*$  by  $\frac{\varepsilon}{2}$  along  $x_n$ -axis, we obtain

$$D_1^\varepsilon := D_1^* + (0', \varepsilon/2) \quad \text{and} \quad D_2^\varepsilon := D_2^* - (0', \varepsilon/2).$$

When there is no confusion, we drop the superscripts  $\varepsilon$  and denote  $D_1 := D_1^\varepsilon$  and  $D_2 := D_2^\varepsilon$ . Denote  $\tilde{\Omega} := \Omega \setminus (\overline{D_1} \cup \overline{D_2})$ . A simple model for electric conduction can be formulated as the following elliptic equation:

$$\begin{cases} \operatorname{div}(a_k(x)\nabla u_k) = 0 & \text{in } \Omega, \\ u_k = \varphi(x) & \text{on } \partial\Omega, \end{cases} \quad (1.1)$$

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where  $\varphi \in C^2(\partial\Omega)$  is given, and

$$a_k(x) = \begin{cases} k \in (0, \infty) & \text{in } D_1 \cup D_2, \\ 1 & \text{in } \tilde{\Omega}, \end{cases}$$

refers to conductivities. The solution  $u_k$  and its gradient  $\nabla u_k$  represent the voltage potential and the electric fields respectively. From an engineering point of view, It is an interesting problem to capture the behavior of  $\nabla u_k$ . Babuška, et al. [3] numerically analyzed that the gradient of solutions to an analogous elliptic system stays bounded regardless of  $\varepsilon$ , the distance between the inclusions. Bonnetier and Vogelius [5] proved that for a fixed  $k$ ,  $|\nabla u_k|$  is bounded for touching disks  $D_1$  and  $D_2$  in dimension  $n = 2$ . A general result was obtained by Li and Vogelius [11] for general second order elliptic equations of divergence form with piecewise Hölder coefficients and general shape of inclusions  $D_1$  and  $D_2$  in any dimension. When  $k$  is bounded away from 0 and  $\infty$ , they established a  $W^{1,\infty}$  bound of  $u_k$  in  $\Omega$ , and a  $C^{1,\alpha}$  bound in each region that do not depend on  $\varepsilon$ . This result was further extended by Li and Nirenberg [10] to general second order elliptic systems of divergence form. Some higher order estimates with explicit dependence on  $r_1, r_2, k$  and  $\varepsilon$  were obtained by Dong and Li [7] for two circular inclusions of radius  $r_1$  and  $r_2$  respectively in dimension  $n = 2$ . There are still some related open problems on general elliptic equations and systems. We refer to p. 94 of [11] and p. 894 of [10].

When the inclusions are insulators ( $k = 0$ ), it was shown in [6,9,13] that the gradient of solutions generally becomes unbounded, as  $\varepsilon \rightarrow 0$ . It was known that (see e.g., Appendix of [4]) when  $k \rightarrow 0$ ,  $u_k$  converges to the solution of the following insulated conductivity problem:

$$\begin{cases} -\Delta u = 0 & \text{in } \tilde{\Omega}, \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial D_i, \quad i = 1, 2, \\ u = \varphi & \text{on } \partial\Omega. \end{cases} \tag{1.2}$$

Here  $\nu$  denotes the inward unit normal vectors on  $\partial D_i, i = 1, 2$ .

The behavior of the gradient in terms of  $\varepsilon$  has been studied by Ammari et al. in [1] and [2], where they considered the insulated problem on the whole Euclidean space:

$$\begin{cases} \Delta u = 0 & \text{in } \mathbb{R}^n \setminus \overline{(D_1 \cup D_2)}, \\ \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial D_i, \quad i = 1, 2, \\ u(x) - H(x) = \mathcal{O}(|x|^{n-1}) & \text{as } |x| \rightarrow \infty. \end{cases} \tag{1.3}$$

They established when dimension  $n = 2$ ,  $D_1^*$  and  $D_2^*$  are disks of radius  $r_1$  and  $r_2$  respectively, and  $H$  is a harmonic function in  $\mathbb{R}^2$ , the solution  $u$  of (1.3) satisfies

$$\|\nabla u\|_{L^\infty(B_4)} \leq C\varepsilon^{-1/2},$$