

# On Fully Decoupled, Convergent Schemes for Diffuse Interface Models for Two-Phase Flow with General Mass Densities

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**Abstract.** In the first part, we study the convergence of discrete solutions to splitting schemes for two-phase flow with different mass densities suggested in [Guillen-Gonzalez, Tierra, J.Comput.Math. (6)2014]. They have been formulated for the diffuse interface model in [Abels, Garcke, Grün, M3AS, 2012, DOI:10.1142/S0218202511500138] which is consistent with thermodynamics. Our technique covers various discretization methods for phase-field energies, ranging from convex-concave splitting to difference quotient approaches for the double-well potential. In the second part of the paper, numerical experiments are presented in two space dimensions to identify discretizations of Cahn-Hilliard energies which are  $\varphi$ -stable and which do not reduce the acceleration of falling droplets. Finally, 3d simulations in axial symmetric geometries are shown to underline even more the full practicality of the approach.

**AMS subject classifications:** 35Q35, 65M60, 65M22, 65M12, 76D05, 76T10

**Key words:** Two-phase flow, Cahn-Hilliard equation, diffuse interface model, convergence of finite-element schemes, numerical simulation.

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## 1 Introduction

In this paper, we are concerned with aspects of numerical analysis and practical computation related to the diffuse interface model for two-phase flow of incompressible, viscous

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fluids with different mass densities proposed in [1]. It reads as follows.

$$\bar{\rho}(\varphi)\partial_t\mathbf{v} + \left( \left( \bar{\rho}(\varphi)\mathbf{v} + \frac{\partial\bar{\rho}(\varphi)}{\partial\varphi}\mathbf{j} \right) \cdot \nabla \right) \mathbf{v} - \nabla \cdot (2\eta(\varphi)\mathbf{D}\mathbf{v}) + \nabla p = \mu\nabla\varphi + \mathbf{k}_{\text{grav}}, \quad (1.1a)$$

$$\partial_t\varphi + \mathbf{v} \cdot \nabla\varphi - \nabla \cdot (M(\varphi)\nabla\mu) = 0, \quad (1.1b)$$

$$\mu = \sigma \left( -\varepsilon\Delta\varphi + \frac{1}{\varepsilon}F'(\varphi) \right), \quad (1.1c)$$

$$\nabla \cdot \mathbf{v} = 0 \quad \text{in } \Omega \times (0, T). \quad (1.1d)$$

Since we wish to take contact angle hysteresis into account, too, the following boundary conditions are chosen.

$$\sigma \frac{\partial\varphi}{\partial\mathbf{n}} = -\gamma'_{LS} - \alpha\partial_t\varphi \quad \text{on } \partial\Omega \times (0, T), \quad (1.2a)$$

$$\frac{\partial}{\partial\mathbf{n}}\mu \equiv 0 \quad \text{on } \partial\Omega \times (0, T), \quad (1.2b)$$

$$\mathbf{v} \equiv 0 \quad \text{on } \partial\Omega \times (0, T). \quad (1.2c)$$

Here,  $\gamma_{LS}(\varphi)$  interpolates between the liquid-solid interfacial energies in the pure phases, and  $\alpha \geq 0$  is the coefficient related to energy dissipation caused by contact line motion. The parameter  $\sigma$  is the surface tension coefficient, which is assumed to be  $\sigma = 1$  in this paper. Note that this approach is inspired by the ideas of [22] where the relationship to contact angle hysteresis is explained. In particular, if  $\gamma_{LS} \equiv \text{const.}$  and  $\alpha \equiv 0$ , the system prefers a contact angle  $\theta$  of 90 degrees, as (1.2a) is a phase-field approximation of Young's law  $\cos\theta = (\gamma_{LS}(-1) - \gamma_{LS}(1))/\sigma$ , see [22]. Note that system (1.1) couples a hydrodynamic momentum equation with a Cahn-Hilliard type phase-field equation.  $F$  is a double-well potential with minima in  $\pm 1$  – representing the pure phases  $\varphi \equiv \pm 1$ . The term  $\mu$  stands for the so called chemical potential, and the order parameter  $\varphi$  stands for the difference of the volume fractions  $u_2 - u_1$  where  $u_i(x, t) := \rho_i(x, t)/\bar{\rho}_i$  with  $\bar{\rho}_i$  the specific (constant) density of fluid  $i$  in a unmixed setting. The parameter  $\varepsilon$  controls the width of the interface region. For the ease of notation we set  $\varepsilon = 1$ . Denoting the individual velocities by  $\mathbf{v}_i$ ,  $i = 1, 2$ , we write  $\mathbf{v} := u_1\mathbf{v}_1 + u_2\mathbf{v}_2$  for the volume averaged velocity. Assuming  $\bar{\rho}_2 \geq \bar{\rho}_1$ , the density of the total mass  $\bar{\rho}(\varphi)$  is given by

$$\bar{\rho}(\varphi) = \frac{\bar{\rho}_2 + \bar{\rho}_1}{2} + \frac{\bar{\rho}_2 - \bar{\rho}_1}{2}\varphi, \quad (1.3)$$

and  $\mathbf{D}\mathbf{v}$  denotes the symmetrized gradient. The term  $\mathbf{k}_{\text{grav}}$  stands for the density of external volume forces. Finally, the flux  $\mathbf{j}$  is defined by  $\mathbf{j} := -M(\varphi)\nabla\mu$  where  $M(\varphi)$  is the mobility.

It is straightforward to show that the physical energy<sup>†</sup>

$$\bar{\mathcal{E}}(\mathbf{v}, \varphi) := \frac{1}{2} \int_{\Omega} \bar{\rho}(\varphi) |\mathbf{v}|^2 + \frac{\varepsilon}{2} \int_{\Omega} |\nabla\varphi|^2 + \frac{1}{\varepsilon} \int_{\Omega} F(\varphi) + \int_{\partial\Omega} \gamma_{LS}(\varphi) \quad (1.4)$$

<sup>†</sup>Note that later in the paper, we will consider regularizations  $\rho(\cdot)$  of  $\bar{\rho}(\cdot)$ . Consistently, we will denote the corresponding energy by  $\mathcal{E}(\mathbf{v}, \varphi)$ .