A Comparative Method for Analysing Toponome Image Stacks

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Abstract. We present a technique to find threshold values that allows the user to separate signal from noise in fluorescence grey-level images. It can be classified as a purely comparative method based upon the amount of “Mutual Information” between two or more fluorescence images, and we apply it to stacks of such images produced using the newly-developed MELK technology. Our results are compared to results obtained by another research group using a quite different (completely independent and more technology-based) approach; and also to results obtained using Otsu’s Thresholding Method, yet another completely distinct approach invented to separate foreground and background in a grey-level image, based on minimising “intra-class variance” [9, 10]. The remarkably good agreement found suggests that our proposed comparative information based method not only accounts for the biological mechanisms governing cellular protein networks very well, but also (and probably much more importantly) shows that cells actually organise the spatial structure of their protein networks in a highly non-random fashion as might be expected – and thereby try to optimise their “mutual information content”, and thus most probably their efficiency.

Key words: MELK technology, Kullback-Leibler distance, threshold values, numerical optimization.

1. Introduction

Given a finite collection ‘C’ of observations, each observation c ∈ ‘C’ being represented by a vector ϕ(c) = (c1, ···, cn) ∈ Rn, there are many areas – from sensing, security, and data mining to biology and medicine – where a pre-processing step assigning a 0, 1-vector

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\( \chi(c) = \tilde{c} = (\tilde{c}_1, \cdots, \tilde{c}_n) \) to each observation \( c \in \mathcal{C} \) can be a great advantage. Clearly, it is appropriate that this assignment be monotone (i.e. \( c, d \in \mathcal{C}, i \in \{1, \cdots, n\} \)), that \( c_i \leq d_i \) should always imply \( \tilde{c}_i \leq \tilde{d}_i \), and that it should maximise the “surprise” (or the “mutual information content”) that can be found in the data, following the “surprisology” paradigm proposed in [14].

The monotonicity requirement is easily met, by choosing a threshold or ‘cut-off’ vector \( t = (t_1, \cdots, t_n) \in \mathbb{R}^n \) that allows us to define a monotone map

\[
\psi_t : \mathbb{R}^n \to \{0, 1\}^n : (x_1, \cdots, x_n) \mapsto (\tilde{x}_1, \cdots, \tilde{x}_n)
\]

by putting

\[
\tilde{x}_i := \begin{cases} 
1 & \text{if } x_i \geq t_i, \\
0 & \text{otherwise}
\end{cases}
\]

for all \( i = 1, \cdots, n \). When composed with \( \varphi \), this yields the required \( \{0, 1\} \) vector \( \tilde{c} = \psi_t(c_1, \cdots, c_n) = \psi_t(\varphi(c)) \) for each observation \( c \in \mathcal{C} \).

We follow the basic exposition already outlined in [2], by assuming that the mutual independence of the observed values \( c_i, i \in \{1, \cdots, n\} \) of any observation \( c \in \mathcal{C} \) (i.e. over all observations in \( \mathcal{C} \)) would not yield a surprise. Then one can measure the ‘amount of surprise’ encountered when associating a \( \{0, 1\} \) vector \( \chi(c) = (\chi_1(c), \cdots, \chi_n(c)) \) to each \( c \in \mathcal{C} \), by comparing the observed probability distribution \( p_\chi \) defined for each \( \varepsilon = (\varepsilon_1, \cdots, \varepsilon_n) \in \{0, 1\}^n \) by

\[
p_\chi(\varepsilon) := \frac{\#\{c \in \mathcal{C} | \chi(c) = \varepsilon\}}{\#\mathcal{C}}
\]

with the expected probability distribution \( q_\chi \) defined by

\[
q_\chi(\varepsilon) := \prod_{i=1}^n \frac{\#\{c \in \mathcal{C} | \chi_i(c) = \varepsilon_i\}}{\#\mathcal{C}}.
\]

Given the independence of the coordinates, note that \( q_\chi \) would essentially coincide with \( p_\chi \). Consequently, noting that \( \varepsilon \in \{0, 1\}^n \) and \( q_\chi(\varepsilon) = 0 \) always implies \( p_\chi(\varepsilon) = 0 \), the well-known Kullback-Leibler Divergence or Mutual-Information Function

\[
MI(q_\chi \to p_\chi) := \sum_{\varepsilon \in \{0, 1\}^n} p_\chi(\varepsilon) \log \left( \frac{p_\chi(\varepsilon)}{q_\chi(\varepsilon)} \right)
\]

(with \( p_\chi(\varepsilon) \ln(p_\chi(\varepsilon) / q_\chi(\varepsilon)) = 0 \) for \( p_\chi(\varepsilon) = 0 \)) appears to be a good measure of that ‘amount of surprise’ encountered by the map \( \chi : \mathcal{C} \to \{0, 1\}^n \) (see e.g., [11], for its various virtues). Thus to each cut-off vector \( t \in \mathbb{R}^n \) one can associate its surprise value \( surp(t) = surp_\chi(\varepsilon, \varphi)(t) \) defined by

\[
surp(t) := MI(q_{\psi_t \varphi} \to p_{\psi_t \varphi})
\]

and declare a cut-off vector \( t \) to be \((\mathcal{C}, \varphi)\)-optimal if

\[
surp(t) \geq surp(t')
\]