

# Existence and Multiplicity of Positive Solutions for a Singular Nonlinear High Order Fractional Differential Problem with Multi-point Boundary Conditions\*

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**Abstract** In this paper, a singular nonlinear high order fractional differential problem involving multi-point boundary conditions is solved by means of the fixed point index theory. Some properties of the first eigenvalue corresponding to relevant operator and some new height functions are also used to prove the existence and multiplicity of positive solutions. The nonlinearity depends on arbitrary fractional derivative.

**Keywords** Positive solutions, Fractional differential problem, Fixed point index, First eigenvalue, Multi-point boundary conditions.

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## 1. Introduction

We strive to investigate the existence and multiplicity of positive solutions for the following fractional equation problem:

$$\begin{cases} D_{0+}^{\alpha}y(t) + g(t)f(t, y(t), D_{0+}^w y(t)) = 0, & 0 < t < 1, \\ D_{0+}^w y(0) = D_{0+}^{w+1}y(0) = \dots = D_{0+}^{w+n-2}y(0) = 0, \\ D_{0+}^{\beta}y(1) = \sum_{i=1}^m \eta_i D_{0+}^{\gamma}y(\zeta_i), \end{cases} \quad (1.1)$$

where  $\alpha \in \mathbb{R}$ ,  $n - 1 < \alpha \leq n$ ,  $n > 2$ ,  $\eta_i \geq 0$ ,  $i = 1, 2, \dots, m$  ( $m \in \mathbb{N}^+$ ),  $0 < \zeta_1 < \zeta_2 < \dots < \zeta_m < 1$ ,  $\beta, \gamma \in \mathbb{R}$ ,  $1 \leq \beta - w$ ,  $\beta \leq n - 2$  and  $0 \leq \gamma \leq \beta$  with  $(\Gamma(\alpha)/\Gamma(\alpha - \gamma)) \sum_{i=1}^m \eta_i \zeta_i^{\alpha-\gamma-1} < \Gamma(\alpha)/\Gamma(\alpha - \beta)$ ,  $0 \leq w \leq 1$ ,  $D_{0+}^{\alpha}$  is the  $\alpha$ -order Riemann-Liouville derivative,  $f(t, u, v) \in C([0, 1] \times [0, +\infty) \times [0, +\infty), [0, +\infty))$ ,  $g(t)$  is continuous and may have singularities at the points  $t = 0, 1$ . Under certain conditions, by using some properties of the first eigenvalue corresponding to relevant operator, the different height functions of the nonlinear term of the equation defined on the special bounded set and theory of the fixed point index, we obtain the existence and multiplicity results of positive solutions.

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In recent years, a large number of fractional differential equations with various boundary conditions have been paid attention to people in many fields such as science and engineering. This is mainly because in most cases we can use such a mathematical model to accurately and quickly solve many complex problems in various fields, such as biology physics, chemistry, control theory, engineering, mechanics, aerodynamics and other fields. For details, see [3, 4, 13, 21, 23, 29]. Recently, extensive research on differential equations has promoted the development of boundary value problems (BVP) of differential equations. They include singular BVP [5, 10, 17, 19, 22, 30], semipositone BVP [1, 9, 16, 24–26] and nonlocal BVP [2, 8, 11, 12, 15, 18, 27] as special cases. The existence, uniqueness and multiplicity of solutions to these problems are obtained by using nonlinear analysis techniques such as the nonlinear alternative technique, fixed point theorems, the method of monotone iterative, upper and lower solutions method. Now, we give some examples. In [19], Jiang et al. explored the following two-term fractional equation problem with two point boundary value problem:

$$\begin{cases} -D_{0+}^{\alpha}x(t) + ax(t) = b(t)f(t, x(t)), & 0 < t < 1, \\ x(0) = 0, \quad x(1) = 0, \end{cases}$$

where  $1 < \alpha \leq 2$ ,  $a > 0$  and  $f : [0, 1] \times [0, \infty) \rightarrow [0, \infty)$  is continuous,  $b(t)$  is continuous and its singularities are  $t = 0, 1$ , by virtue of  $u_0$ -positive operator and theory of the fixed point index, at least one positive solution has been found. In [28], Zhang *et al.* studied the following differential equation, which is an integral boundary value problem:

$$\begin{cases} D_{0+}^{\alpha}x(t) + f(t, x(t)) = 0, & 0 < t < 1, \\ x^{(\beta)}(0) = 0, & 0 \leq \beta \leq n - 2, \\ [D_{0+}^{\gamma}x(t)]_{t=1} = \lambda \int_0^{\eta} g(t)D_{0+}^{\gamma}x(t)dt, \end{cases}$$

where  $D_{0+}^{\alpha}$  is the Riemann-Liouville fractional derivative,  $n - 1 < \alpha \leq n$ ,  $n \geq 3$ ,  $\gamma \geq 1$ ,  $\alpha - \gamma - 1 > 0$ ,  $\eta \in (0, 1]$ ,  $0 \leq \lambda \int_0^{\eta} g(t)t^{\alpha-\gamma-1}dt < 1$ ,  $g \in L^1[0, 1]$  is nonnegative, the singularities of  $f(t, x)$  are  $t = 0, 1$  and  $x = 0$ . By using Leggett-Williams fixed point theory, the authors demonstrated that the equation at least has three positive solutions. In [12], He et al. explored the following differential problem with the Riemann-Stieltjes integral and with any derivative in the integral:

$$\begin{cases} D_{0+}^{\alpha}x(t) + f(t, x(t), D_{0+}^{\beta}x(t)) = 0, & 0 < t < 1, \\ D_{0+}^{\beta}x(0) = D_{0+}^{\beta+1}x(0) = 0, \\ [D_{0+}^{\gamma}x(t)]_{t=1} = \int_0^1 D_{0+}^{\gamma}x(s)dA(s), \end{cases}$$

where  $D_{0+}^{\alpha}$  is the Riemann-Liouville derivative,  $2 < \alpha \leq 3$ ,  $0 < \beta \leq \gamma < \alpha - 2$ ,  $\int_0^1 D_{0+}^{\gamma}x(s)dA(s)$  is a linear functional with the Riemann-Liouville integrals, the singularities of  $f(t, u, v)$  are  $t = 0, 1$  and  $u = v = 0$ , by applying suitable upper and lower solutions and Schauder's fixed point theorem, the authors proved that the problem at least has one positive solution.

Motivated by all the papers above, we discuss the existence and multiplicity of positive solutions of (1.1). Our article have various features. Firstly, the equation

we study is a high order fractional differential equation. Compared with literature [12, 19], our equation is more general. Secondly, the nonlinear term is dependent on any derivative and the boundary value conditions are also related to any derivative, this is different from [19]. Thirdly, we study (1.1) by virtue of some properties of the first eigenvalue corresponding to relevant operator and some new height functions, some sufficient conditions for the existence and multiplicity of positive solutions are established. The method used is different from [12, 19, 28]. Therefore, our conclusion are new and meaningful.

The remaining part of the paper is arranged as follows: We will state the basic definition and we will summarise the properties of Green's function in the next section. In addition, we will give key lemmas. Section 3 is devoted to prove that (1.1) has at least one solution and at least three solutions.

## 2. Preliminaries

For the convenience of understanding, we first give some definitions and lemmas, which will play a crucial role in the process of proving our conclusion.

**Definition 2.1** ([20]). The Riemann-Liouville fractional integral of order  $\alpha > 0$  for a function  $y : (0, \infty) \rightarrow \mathbb{R}$  is defined as

$$I_{0+}^{\alpha}y(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1}y(s)ds,$$

which provided the right-hand side of the equation is pointwise defined on  $(0, \infty)$ .

**Definition 2.2** ([20]). The Riemann-Liouville fractional derivative of order  $\alpha > 0$  for a continuous function  $y : (0, \infty) \rightarrow \mathbb{R}$  is defined as

$$\mathcal{D}_{0+}^{\alpha}y(t) = \frac{1}{\Gamma(n-\alpha)} \left(\frac{d}{dt}\right)^n \int_0^t \frac{y(s)}{(t-s)^{\alpha-n+1}}ds,$$

where  $n$  is the smallest integer greater than or equal to  $\alpha$ , providing the right-hand side of the equation is pointwise defined on  $(0, \infty)$ .

**Lemma 2.1** ([25]). (i) If  $y \in L^1(0, 1)$ ,  $\mu > \sigma > 0$ , then

$$I_{0+}^{\mu}I_{0+}^{\sigma}y(t) = I_{0+}^{\mu+\sigma}y(t), \quad D_{0+}^{\sigma}I_{0+}^{\mu}y(t) = I_{0+}^{\mu-\sigma}y(t), \quad D_{0+}^{\sigma}I_{0+}^{\sigma}y(t) = y(t). \quad (2.1)$$

(ii) If  $\mu > 0, \sigma > 0$ , then

$$D_{0+}^{\mu}t^{\sigma-1} = \frac{\Gamma(\sigma)}{\Gamma(\sigma-\mu)}t^{\sigma-\mu-1}. \quad (2.2)$$

Let  $y(t) = I_{0+}^w z(t)$ , where  $z(t) \in C[0, 1]$ . By using Lemma 2.1 and the definition of Riemann-Liouville derivative, one has

$$\begin{aligned} D_{0+}^{\alpha}y(t) &= \left(\frac{d}{dt}\right)^n I_{0+}^{n-\alpha}y(t) = \left(\frac{d}{dt}\right)^n I_{0+}^{n-\alpha}I_{0+}^w z(t) = \left(\frac{d}{dt}\right)^n I_{0+}^{n-\alpha+w}z(t) = D_{0+}^{\alpha-w}z(t), \\ D_{0+}^w y(t) &= D_{0+}^w I_{0+}^w z(t) = z(t), \\ D_{0+}^{\mu+w}y(t) &= D_{0+}^{\mu}z(t), \quad D_{0+}^{\nu+w}y(t) = D_{0+}^{\nu}z(t). \end{aligned} \quad (2.3)$$

Let  $\beta - w = \mu$ ,  $\gamma - w = \nu$ . Then, by (2.3), BVP (1.1) can be simplified to the following improved fractional equation:

$$\begin{cases} D_{0+}^{\alpha-w} z(t) + g(t)f(t, I_{0+}^w z(t), z(t)) = 0, & 0 < t < 1, \\ z(0) = z'(0) = \dots = z^{(n-2)}(0) = 0, \\ D_{0+}^{\mu} z(1) = \sum_{i=1}^m \eta_i D_{0+}^{\nu} z(\zeta_i), \end{cases} \quad (2.4)$$

and conversely, by using (2.3) again, we can convert (2.4) into the form (1.1). Therefore, BVP (2.4) and BVP (1.1) are equivalent.

**Lemma 2.2.** *Let  $z \in C[0, 1]$ . If  $z > 0$  is a solution of BVP (2.4), then  $I_{0+}^w z > 0$  is a solution of BVP (1.1).*

**Proof.** Let  $z \in C[0, 1]$  and  $z > 0$  is a solution to the BVP (2.4). Now, for the function  $y(t) = I_{0+}^w z(t)$ , from Lemma 2.1, we have

$$\begin{aligned} D_{0+}^{\alpha} y(t) &= D_{0+}^{\alpha} I_{0+}^w z(t) = D_{0+}^{\alpha-w} z(t) \\ &= -g(t)f(t, I_{0+}^w z(t), z(t)) \\ &= -g(t)f(t, y(t), D_{0+}^w y(t)). \end{aligned} \quad (2.5)$$

In addition, by combining  $y(t) = I_{0+}^w z(t)$ , (2.3), and the boundary conditions of problem (2.4), we get

$$\begin{aligned} D_{0+}^w y(0) &= D_{0+}^{w+1} y(0) = \dots = D_{0+}^{w+n-2} y(0) = 0, \\ D_{0+}^{\beta} y(1) &= \sum_{i=1}^m \eta_i D_{0+}^{\gamma} y(\zeta_i). \end{aligned} \quad (2.6)$$

Thus, we obtain  $I_{0+}^w z(t) > 0$  is a solution of BVP (1.1).  $\square$

**Remark 2.1.** The expression can be obtained by applying the formula calculation,

$$\begin{aligned} I_{0+}^w t^{\alpha-w-1} &= \frac{1}{\Gamma(w)} \int_0^t (t-s)^{w-1} s^{\alpha-w-1} ds \\ &= \frac{B(w, \alpha-w)}{\Gamma(w)} t^{\alpha-1} = \frac{\Gamma(\alpha-w)}{\Gamma(\alpha)} t^{\alpha-1}. \end{aligned} \quad (2.7)$$

Next, we denote  $\Delta = \frac{\Gamma(\alpha-w)}{\Gamma(\alpha-w-\beta)} - \frac{\Gamma(\alpha-w)}{\Gamma(\alpha-w-\gamma)} \sum_{i=1}^m \eta_i \zeta_i^{\alpha-w-\gamma-1}$ .

**Lemma 2.3** ([14]). *Suppose that  $\Delta \neq 0$ . Given  $h \in C(0, 1) \cap L^1(0, 1)$ , then the unique positive solution of the fractional equation:*

$$\begin{cases} D_{0+}^{\alpha-w} z(t) + h(t) = 0, & 0 < t < 1, \\ z(0) = z'(0) = \dots = z^{(n-2)}(0) = 0, \\ D_{0+}^{\mu} z(1) = \sum_{i=1}^m \eta_i D_{0+}^{\nu} z(\zeta_i), \end{cases} \quad (2.8)$$

can be expressed as

$$z(t) = \int_0^1 G(t, s)h(s)ds, \quad t \in [0, 1],$$

where

$$\begin{aligned} G(t, s) &= K_1(t, s) + \frac{t^{\alpha-w-1}}{\Delta} \sum_{i=1}^m \eta_i K_2(\zeta_i, s), \\ K_1(t, s) &= \begin{cases} \frac{t^{\alpha-w-1}(1-s)^{\alpha-w-\mu-1}}{\Gamma(\alpha-w)}, & 0 \leq t \leq s \leq 1, \\ \frac{t^{\alpha-w-1}(1-s)^{\alpha-w-\mu-1} - (t-s)^{\alpha-w-1}}{\Gamma(\alpha-w)}, & 0 \leq s \leq t \leq 1, \end{cases} \\ K_2(t, s) &= \begin{cases} \frac{t^{\alpha-w-\nu-1}(1-s)^{\alpha-w-\mu-1}}{\Gamma(\alpha-w-\nu)}, & 0 \leq t \leq s \leq 1, \\ \frac{t^{\alpha-w-\nu-1}(1-s)^{\alpha-w-\mu-1} - (t-s)^{\alpha-w-\nu-1}}{\Gamma(\alpha-w-\nu)}, & 0 \leq s \leq t \leq 1. \end{cases} \end{aligned} \quad (2.9)$$

Here,  $G(t, s)$  is the Green function for problem (2.8). Obviously, for  $t, s \in [0, 1]$ ,  $G(t, s)$  is continuous.

**Lemma 2.4** ([14]). *If  $\eta_i > 0$ ,  $i = 1, 2, \dots, m$ , and  $\Delta > 0$ , then the function  $G(t, s)$  given by (2.9) has the following essential properties:*

- (i)  $G(t, s) \leq D(s)$ ,  $\forall t, s \in [0, 1]$ , and here  $D(s) = a_1(s) + (1/\Delta) \sum_{i=1}^m \eta_i K_2(\zeta_i, s)$ ,  $a_1(s) = (1-s)^{\alpha-w-\mu-1}(1-(1-s)^\mu)/\Gamma(\alpha-w)$  and  $s \in [0, 1]$ ;
- (ii)  $G(t, s) \geq t^{\alpha-w-1}D(s)$ ,  $\forall t, s \in [0, 1]$ ;
- (iii)  $G(t, s) \leq \delta t^{\alpha-w-1}$ ,  $\forall t, s \in [0, 1]$ , and  $\delta = 1/\Gamma(\alpha-w) + \sum_{i=1}^m \eta_i \zeta_i^{\alpha-w-\nu-1}/(\Delta\Gamma(\alpha-w-\nu))$ .

For the sake of convenience, we present the following hypothesis for the full text.

(H<sub>1</sub>)  $f : [0, 1] \times [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is continuous.

(H<sub>2</sub>)  $g : (0, 1) \rightarrow [0, +\infty)$  is continuous and  $g(t) \not\equiv 0$  on any subinterval of  $(0, 1)$  satisfies  $0 < \int_0^1 D(s)g(s)ds < +\infty$ .

Let  $E = C[0, 1]$ ,  $\|z\| = \max_{0 \leq t \leq 1} |z(t)|$ , then  $(E, \|\cdot\|)$  be a Banach space. Set  $P = \{z \in E : z(t) \geq 0, t \in [0, 1]\}$  is a cone in  $E$ . We define a subcone  $X$  of  $P$

$$X = \{z \in P : z(t) \geq t^{\alpha-w-1}\|z\|, t \in [0, 1]\}.$$

For any  $r > 0$ , let  $X_r = \{z \in X : \|z\| < r\}$ ,  $\partial X_r = \{z \in X : \|z\| = r\}$ ,  $\bar{X}_r = \{z \in X : \|z\| \leq r\}$ . Let  $0 < a_1 < a_2 \leq 1$ , denote  $b = \min_{t \in [a_1, a_2]} t^{\alpha-w-1}$  and  $\xi(z) = \min_{t \in [a_1, a_2]} z(t)$ ,  $z \in X$ .  $\forall R \geq r > 0$ , set  $X(\xi, r, R) = \{z \in X : r \leq \xi(z), \|z\| \leq R\}$ ,  $\dot{X}(\xi, r, R) = \{z \in X : r < \xi(z), \|z\| \leq R\}$ .

Define two operators  $T_0$  and  $T_1$  as follows:

$$(T_0 z)(t) = \int_0^1 G(t, s)g(s)z(s)ds, \quad t \in [0, 1], \quad (2.10)$$

$$(T_1 z)(t) = \int_0^1 G(t, s)g(s)f(s, I_{0+}^w z(s), z(s))ds, \quad t \in [0, 1], \quad (2.11)$$

where  $T_0$  is a linear operator and  $T_1$  is a nonlinear operator. It is not hard to prove that  $T_0 : E \rightarrow E$  is linear completely continuous and  $T_0(P) \subset P$ .

**Lemma 2.5** (Krein-Rutmann [6]). *Assume that  $T_0 : E \rightarrow E$  is linear completely continuous operator and  $T_0(P) \subset P$ . If there are  $\psi \in E \setminus (-P)$  and a constant  $c_1 > 0$  such that  $c_1 T_0(\psi) \geq \psi$ , then the spectral radius  $r(T_0) \neq 0$  and  $T_0$  has a positive eigenfunction  $\varphi_0 > 0$  corresponding to its first eigenvalue  $\lambda_1 = (r(T_0))^{-1}$ . That is,  $\varphi_0 = \lambda_1 T_0 \varphi_0$ .*

From Lemma 2.4 and Lemma 2.5, we know the spectral radius  $r(T_0) \neq 0$ . In addition,  $T_0$  has a eigenfunction  $\varphi_0(t) > 0$  corresponding to its first eigenvalue  $\lambda_1 = (r(T_0))^{-1}$ .

**Lemma 2.6.** *Assume that  $(H_1)$  and  $(H_2)$  hold, then  $T_1 : \overline{X}_{r_2} \setminus X_{r_1} \rightarrow X$  is completely continuous.*

**Proof.** First, we prove  $T_1(\overline{X}_{r_2} \setminus X_{r_1}) \subset X$ . For any  $z \in \overline{X}_{r_2} \setminus X_{r_1}$ ,  $t \in [0, 1]$ , by the definition of  $T_1$  and Lemma 2.4, it implies that

$$\begin{aligned} (T_1 z)(t) &= \int_0^1 G(t, s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\geq t^{\alpha-w-1} \int_0^1 D(s)g(s)f(s, I_{0+}^w z(s), z(s))ds, \end{aligned}$$

and

$$(T_1 z)(t) \leq \int_0^1 D(s)g(s)f(s, I_{0+}^w z(s), z(s))ds,$$

which yield

$$(T_1 z)(t) \geq t^{\alpha-w-1} \|T_1 z\|.$$

Therefore,  $T_1 z \in X$ . That is,  $T_1(\overline{X}_{r_2} \setminus X_{r_1}) \subset X$ . Then, by the standard argument, we obtain that  $T_1 : \overline{X}_{r_2} \setminus X_{r_1} \rightarrow X$  is completely continuous.  $\square$

**Lemma 2.7** ([7]). *Let  $E$  be Banach space.  $X \subset E$  is a cone. Assume that  $T_1 : \overline{X}_{r_1} \rightarrow X$  is completely continuous.*

- (i) *If there is  $z_0 \in X \setminus \{\theta\}$  such that  $z - T_1 z \neq \mu z_0$ , for  $\mu \geq 0$ ,  $z \in \partial X_{r_1}$ , then  $i(T_1, X_{r_1}, X) = 0$ .*
- (ii) *If  $T_1 z \neq \mu z$ , for  $\mu \geq 1$ ,  $z \in \partial X_{r_1}$ , then  $i(T_1, X_{r_1}, X) = 1$ .*

**Lemma 2.8** ([7]). *Let  $T_1 : \overline{X}_{r_3} \rightarrow X$  be completely continuous operator. If there is a concave functional  $\xi > 0$  and  $\xi(z) \leq \|z\|$  ( $z \in X$ ), for positive numbers  $c_1 < c_2 \leq c_3$ , satisfying the conditions:*

- (i)  $\hat{X}(\xi, c_1, c_2) \neq \emptyset$  with  $\xi(T_1 z) > c_1$  if  $z \in X(\xi, c_1, c_2)$ ;
- (ii)  $T_1 z \in \overline{X}_{c_3}$  if  $z \in X(\xi, c_1, c_3)$ ;
- (iii)  $\xi(T_1 z) > c_1$  for  $z \in X(\xi, c_1, c_3)$  with  $\|T_1 z\| > c_2$ .

Then,  $i(T_1, \hat{X}(\xi, c_1, c_3), \overline{X}_{c_3}) = 1$ .

**Lemma 2.9** ([7], [28]). Let  $X$  be a cone in the Banach space  $E$ , and operator  $T_1 : X \rightarrow X$  is completely continuous. Let positive numbers be  $c_1 < c_2 < c_3$ .

(i) If  $\|T_1 z\| > \|z\|$  for any  $z \in \partial X_{c_1}$ , and  $\|T_1 z\| \leq \|z\|$  for any  $z \in \partial X_{c_2}$ , then

$$i(T_1, \overline{X}_{c_2} \setminus \overline{X}_{c_1}, \overline{X}_{c_2}) = 1.$$

(ii) If  $\|T_1 z\| > \|z\|$  for any  $z \in \partial X_{c_1}$ , and  $\|T_1 z\| < \|z\|$  for any  $z \in \partial X_{c_2}$ , then

$$i(T_1, X_{c_2} \setminus \overline{X}_{c_1}, \overline{X}_{c_3}) = 1.$$

### 3. Main results

In the following, we can give the existence and multiplicity results of positive solutions in this paper.

**Theorem 3.1.** Assume that  $(H_1)$  and  $(H_2)$  hold, and

$$\liminf_{\substack{u \rightarrow 0^+ \\ v \rightarrow 0^+}} \frac{f(t, u, v)}{u + v} > \lambda_1, \quad \limsup_{\substack{u+v \rightarrow +\infty \\ v \rightarrow +\infty}} \frac{f(t, u, v)}{v} < \lambda_1, \quad (3.1)$$

uniformly on  $t \in [0, 1]$ , where  $\lambda_1$  is the first eigenvalue of  $T_0$  and  $T_0$  is defined by (2.10). Then, BVP (1.1) at least has a positive solution.

**Proof.** According to (3.1), for  $t \in [0, 1]$ , there exists  $r_1 > 0$  such that

$$f(t, u, v) \geq \lambda_1(u + v), \quad 0 \leq u \leq \frac{r_1}{\Gamma(w+1)}, \quad 0 \leq v \leq r_1, \quad (3.2)$$

and so for  $z \in \partial X_{r_1}$ , since

$$0 \leq I_{0+}^w z(s) \leq \frac{r_1}{\Gamma(w+1)}, \quad 0 \leq z(s) \leq r_1. \quad (3.3)$$

Then, by (3.2), (3.3) and Lemma 2.4, for  $t \in [0, 1]$ , we can get

$$\begin{aligned} (T_1 z)(t) &= \int_0^1 G(t, s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\geq \lambda_1 \int_0^1 G(t, s)g(s)(I_{0+}^w z(s) + z(s))ds \\ &\geq \lambda_1(T_0 z)(t). \end{aligned} \quad (3.4)$$

Let  $\varphi_0 > 0$  be the eigenfunction of  $T_0$  corresponding to  $\lambda_1$ , so  $\varphi_0 = \lambda_1 T_0 \varphi_0$ . Then, we will prove the condition (i) of Lemma 2.7. That is,

$$z - T_1 z \neq \mu \varphi_0, \quad \mu \geq 0, \quad z \in \partial X_{r_1}. \quad (3.5)$$

We use the contraction method. That is, there are  $z_1 \in \partial X_{r_1}$  and  $\mu_1 \geq 0$  such that  $z_1 - T_1 z_1 = \mu_1 \varphi_0$ . Therefore, when  $\mu_1 > 0$ ,  $z_1 = T_1 z_1 + \mu_1 \varphi_0 \geq \mu_1 \varphi_0$ . Set  $\bar{\mu} = \sup\{\mu | z_1 \geq \mu \varphi_0\}$ , then  $\bar{\mu} \geq \mu_0 > 0$ ,  $z_1 \geq \bar{\mu} \varphi_0$ . By (3.4)

$$z_1 = T_1 z_1 + \mu_1 \varphi_0 \geq \lambda_1 T_0 z_1 + \mu_1 \varphi_0 \geq \bar{\mu} \varphi_0 + \mu_1 \varphi_0 = (\bar{\mu} + \mu_1) \varphi_0,$$

this contradicts the definition of  $\bar{\mu}$ . Therefore, (3.5) is established. Then, according to Lemma 2.7, we obtain

$$i(T_1, X_{r_1}, X) = 0. \quad (3.6)$$

Next, we will verify the condition (ii) of Lemma 2.7. According to (3.1), for  $t \in [0, 1]$ , there exists  $r_0 > r_1$  such that

$$f(t, u, v) \leq \lambda_1 v, \quad u + v \geq r_0, v \geq r_0. \quad (3.7)$$

Now, let  $M_1 = \max\{f(t, u, v) | t \in [0, 1], 0 \leq u + v \leq r_0, 0 \leq v \leq r_0\} < +\infty$ . Then, by (3.7) and for  $t \in [0, 1]$ , we have

$$f(t, u, v) \leq \lambda_1 v + M_1, \quad u + v \geq 0, v \geq 0. \quad (3.8)$$

Set

$$A = \{z \in X, z = \mu T_1 z, 0 \leq \mu \leq 1\}.$$

Next, we prove that  $A$  is bounded. For  $\mu \in [0, 1]$  and  $z \in A$ , from (3.8), we obtain

$$\begin{aligned} z(t) = \mu(T_1 z)(t) &\leq \int_0^1 G(t, s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\leq \int_0^1 G(t, s)g(s)[\lambda_1 z + M_1]ds \\ &\leq \lambda_1(T_0 z)(t) + N, \end{aligned} \quad (3.9)$$

where  $N = M_1 \sup_{t \in [0, 1]} \int_0^1 G(t, s)g(s)ds$ . We know  $r(\lambda_1 T_0) < 1$ , so  $I - \lambda_1 T_0$  is reversible.  $I$  is the identity operator. Then,

$$(I - \lambda_1 T_0)^{-1} = I + \lambda_1 T_0 + (\lambda_1 T_0)^2 + \cdots + (\lambda_1 T_0)^n + \cdots.$$

According to  $T_0 : P \rightarrow P$ , we have  $(I - \lambda_1 T_0)^{-1}(P) \subset P$ . Then, this together with (3.9) imply

$$z(t) \leq (I - \lambda_1 T_0)^{-1}N, \quad t \in [0, 1].$$

Thus, we get  $A$  is bounded.

We choose  $r_2 > \max\{r_0, \sup A\}$ , then we can easily get

$$z \neq \mu T_0 z, \quad z \in \partial X_{r_2}, 0 \leq \mu \leq 1.$$

Then, according to Lemma 2.7, we get

$$i(T_1, X_{r_2}, X) = 1. \quad (3.10)$$

By (3.6) and (3.10), we get

$$i(T_1, X_{r_2} \setminus \bar{X}_{r_1}, X) = i(T_1, X_{r_2}, X) - i(T_1, X_{r_1}, X) = 1.$$



Consequently,  $T_1$  at least has a fixed point. That is, BVP (2.4) has a solution  $z > 0$ . From Lemma 2.2, then BVP (1.1) has a positive solution  $y = I_{0+}^w z$ .  $\square$

Before giving the rest of the paper, we define some height functions.

$$\phi(t, r_1, r_2) = \max \left\{ f(t, u, v) : r_1 m_1(t) \leq u \leq \frac{r_2 t^w}{\Gamma(w+1)}, r_1 m_2(t) \leq v \leq r_2 \right\},$$

$$\phi(t, r) = \max \left\{ f(t, u, v) : r m_1(t) \leq u \leq \frac{r t^w}{\Gamma(w+1)}, r m_2(t) \leq v \leq r \right\},$$

$$\varphi_1(t, r) = \min \left\{ f(t, u, v) : r m_1(t) \leq u \leq \frac{r t^w}{\Gamma(w+1)}, r m_2(t) \leq v \leq r \right\},$$

$$\varphi_2(t, r_1, r_2) = \min \left\{ f(t, u, v) : \frac{r_1 t^w}{\Gamma(w+1)} \leq u \leq \frac{r_2 t^w}{\Gamma(w+1)}, r_1 \leq v \leq r_2 \right\},$$

where  $m_1(t) = \frac{\Gamma(\alpha-w)}{\Gamma(\alpha)} t^{\alpha-1}$  and  $m_2(t) = t^{\alpha-w-1}$ .

**Theorem 3.2.** Assume that  $(H_1)$  and  $(H_2)$  hold, and there exist constants  $k_i$ ,  $i = 1, \dots, 5$  with  $0 < k_1 < k_2 < k_3 < k_4 < k_5$  and  $k_3 < b k_4$  such that

$$(S_1) \int_0^1 D(s)g(s)\varphi_1(s, k_1)ds \geq k_1;$$

$$(S_2) \int_0^1 D(s)g(s)\phi(s, k_2)ds < k_2;$$

$$(S_3) \int_{a_1}^{a_2} D(s)g(s)\varphi_2(s, k_3, k_4)ds > k_3 b^{-1};$$

$$(S_4) \int_0^1 D(s)g(s)\phi(s, k_3, k_5)ds \leq k_5.$$

Then, BVP (1.1) at least has three positive solutions.

**Proof.** By Lemma 2.6, when  $r_1 = k_1$  and  $r_2 = k_5$ , for any  $z \in \overline{X}_{k_5} \setminus X_{k_1}$ ,  $t \in [0, 1]$ , we have  $k_1 m_2(t) \leq z(t) \leq k_5$  and  $k_1 m_1(t) \leq I_{0+}^w z(t) \leq \frac{k_5 t^w}{\Gamma(w+1)}$ . We know  $T_1 : \overline{X}_{k_5} \setminus X_{k_1} \rightarrow X$  is completely continuous. According to the extension theorem,  $\tilde{T}_1 : X \rightarrow X$  is a completely continuous operator extended from  $T_1$ . We will still use  $T_1$  to represent it below. First, we confirm that all the conditions of Lemma 2.8 are satisfied. Then,  $i(T_1, \overset{\circ}{X}(\xi, k_3, k_5), \overline{X}_{k_5}) = 1$ .

(i) Obviously,  $\overset{\circ}{X}(\xi, k_3, k_4) \neq \emptyset$ . For  $z \in X(\xi, k_3, k_4)$  and  $t \in [a_1, a_2] \subset (0, 1]$ , we have  $k_3 \leq z(t) \leq k_4$  and  $\frac{k_3 t^w}{\Gamma(w+1)} \leq I_{0+}^w z(t) \leq \frac{k_4 t^w}{\Gamma(w+1)}$ . According to Lemma 2.4 and assumption  $(S_3)$ ,

$$\begin{aligned} \xi(T_1 z) &\geq \min_{t \in [a_1, a_2]} t^{\alpha-w-1} \int_{a_1}^{a_2} D(s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\geq b \int_{a_1}^{a_2} D(s)g(s)\varphi_2(s, k_3, k_4)ds > k_3. \end{aligned} \quad (3.11)$$

(ii) For  $z \in X(\xi, k_3, k_5)$  and  $t \in [0, 1]$ , we have

$$k_3 m_2(t) \leq z(t) \leq k_5, \quad k_3 m_1(t) \leq I_{0+}^w z(t) \leq \frac{k_5 t^w}{\Gamma(w+1)}. \quad (3.12)$$

According to Lemma 2.4 and assumption  $(S_4)$ ,

$$\begin{aligned} (T_1 z)(t) &\leq \int_0^1 D(s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\leq \int_0^1 D(s)g(s)\phi(s, k_3, k_5)ds \leq k_5. \end{aligned} \quad (3.13)$$

Consequently, we obtain  $T_1 z \in \overline{X}_{k_5}$ .

(iii) For  $z \in X(\xi, k_3, k_5)$ ,  $t \in [a_1, a_2]$  and  $\|T_1 z\| > k_4$ , obviously,  $bk_4 \geq k_3$ . Then, we have

$$\begin{aligned} \xi(T_1 z) &= \min_{t \in [a_1, a_2]} (T_1 z)(t) \geq \min_{t \in [a_1, a_2]} t^{\alpha-w-1} \|T_1 z\| \\ &= b \|T_1 z\| > bk_4 \geq k_3. \end{aligned} \quad (3.14)$$

Therefore, from Lemma 2.8, when  $c_1 = k_3$ ,  $c_2 = k_4$ ,  $c_3 = k_5$ , we get the conclusion that

$$i(T_1, \mathring{X}(\xi, k_3, k_5), \overline{X}_{k_5}) = 1. \quad (3.15)$$

Next, for  $z \in \partial X_{k_5}$ , obviously,  $\|z\| = k_5$ , and for  $t \in [0, 1]$ , we have  $k_3 m_2(t) \leq k_5 m_2(t) \leq z(t) \leq k_5$  and  $k_3 m_1(t) \leq k_5 m_1(t) \leq I_{0+}^w z(t) \leq \frac{k_5 t^w}{\Gamma(w+1)}$ . Therefore, (3.12) holds. Then, by (3.12), Lemma 2.4 and assumption  $(S_4)$ , in the same way that we proved (3.13), we have

$$\|T_1 z\| \leq k_5, \quad \forall z \in \partial X_{k_5}. \quad (3.16)$$

For  $z \in \partial X_{k_2}$  and  $t \in [0, 1]$ , we have  $k_2 m_2(t) \leq z(t) \leq k_2$  and  $k_2 m_1(t) \leq I_{0+}^w z(t) \leq \frac{k_2 t^w}{\Gamma(w+1)}$ . According to Lemma 2.4 and assumption  $(S_2)$ , we can obtain

$$\begin{aligned} (T_1 z)(t) &\leq \int_0^1 D(s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\leq \int_0^1 D(s)g(s)\phi(s, k_2)ds < k_2. \end{aligned}$$

Then,

$$\|T_1 z\| < k_2, \quad \forall z \in \partial X_{k_2}. \quad (3.17)$$

For  $z \in \partial X_{k_1}$  and  $t \in [0, 1]$ , we obtain  $k_1 m_2(t) \leq z(t) \leq k_1$  and  $k_1 m_1(t) \leq I_{0+}^w z(t) \leq \frac{k_1 t^w}{\Gamma(w+1)}$ . According to Lemma 2.4 and assumption  $(S_1)$ , we have

$$\begin{aligned} (T_1 z)(t) &\geq t^{\alpha-w-1} \int_0^1 D(s)g(s)f(s, I_{0+}^w z(s), z(s))ds \\ &\geq t^{\alpha-w-1} \int_0^1 D(s)g(s)\varphi_1(s, k_1)ds, \end{aligned}$$

which yields

$$\|T_1 z\| \geq \max_{t \in [0, 1]} t^{\alpha-w-1} \int_0^1 D(s)g(s)\varphi_1(s, k_1)ds = \int_0^1 D(s)g(s)\varphi_1(s, k_1)ds \geq k_1, \quad \forall z \in \partial X_{k_1}. \quad (3.18)$$

Therefore, by (3.16), (3.17), (3.18) and Lemma 2.9, we obtain

$$i(T_1, \overline{X}_{k_5} \setminus \overline{X}_{k_1}, \overline{X}_{k_5}) = 1, \quad (3.19)$$

$$i(T_1, X_{k_2} \setminus \overline{X}_{k_1}, \overline{X}_{k_5}) = 1. \quad (3.20)$$

From (3.18), it is obvious that  $T_1$  has no fixed point on  $\partial X_{k_2}$ . Moreover, for  $z \in X(\xi, k_3, k_4)$ , by (3.11), we can get  $\xi(T_1 z) > k_3$ . Then, for  $z \in X(\xi, k_3, k_5)$  with  $\|T_1 z\| > k_4$ , we also get  $\xi(T_1 z) > k_3$ . Therefore,  $T_1$  has no fixed point on  $X(\xi, k_3, k_5) \setminus \overset{\circ}{X}(\xi, k_3, k_5)$ .

It follows from (3.15), (3.19) and (3.20) that

$$\begin{aligned} & i(T_1, \overline{X}_{k_5} \setminus (X(\xi, k_3, k_5) \cup \overline{X}_{k_2}), \overline{X}_{k_5}) \\ &= i(T_1, \overline{X}_{k_5} \setminus \overline{X}_{k_1}, \overline{X}_{k_5}) - i(T_1, X_{k_2} \setminus \overline{X}_{k_1}, \overline{X}_{k_5}) \\ & - i(T_1, \overset{\circ}{X}(\xi, k_3, k_5), \overline{X}_{k_5}) = -1. \end{aligned} \quad (3.21)$$

Consequently, by (3.15), (3.20) and (3.21), we conclude that  $T_1$  at least has three fixed points  $z_1 \in X_{k_2} \setminus \overline{X}_{k_1}$ ,  $z_2 \in \overset{\circ}{X}(\xi, k_3, k_5)$  and  $z_3 \in \overline{X}_{k_5} \setminus (X(\xi, k_3, k_5) \cup \overline{X}_{k_2})$ . Clearly,  $y_i = I_{0+}^w z_i$ ,  $i = 1, 2, 3$ , are three positive solutions of BVP (1.1).  $\square$

## 4. An example

**Example 4.1.** Consider the following equation

$$\begin{cases} -D_{0+}^{\frac{7}{2}} y(t) = g(t)f(t, y(t), D_{0+}^{\frac{1}{4}} y(t)), & 0 < t < 1, \\ D_{0+}^{\frac{1}{4}} y(0) = D_{0+}^{\frac{5}{4}} y(0) = D_{0+}^{\frac{3}{4}} y(0) = 0, \\ D_{0+}^{\frac{7}{4}} y(1) = \frac{2}{3} D_{0+}^{\frac{3}{2}} y(0.8). \end{cases} \quad (4.1)$$

where  $\alpha = \frac{7}{2}$ ,  $n = 4$ ,  $w = \frac{1}{4}$ ,  $\beta = \frac{7}{4}$ ,  $\gamma = \frac{3}{2}$ ,  $g(t) = \frac{5}{\sqrt[4]{t(1-t)}}$ ,  $f(t, y(t), D_{0+}^{\frac{1}{4}} y(t)) = (D_{0+}^{\frac{1}{4}} y(t))^{-\frac{1}{8}} + [y(t) + D_{0+}^{\frac{1}{4}} y(t)]^{-\frac{1}{4}}$ . By direct computation, we have  $(\Gamma(\alpha)/\Gamma(\alpha - \gamma)) \sum_{i=1}^m \eta_i \zeta_i^{\alpha-\gamma-1} = (\Gamma(\frac{7}{2})/\Gamma(2)) \times \frac{2}{3} \times 0.8 \approx 1.7728 < \Gamma(\frac{7}{2})/\Gamma(\frac{7}{4}) = 3.6142$  and  $\Delta \approx 1.3129 > 0$ . Obviously,  $f : [0, 1] \times [0, +\infty) \times [0, +\infty) \rightarrow [0, +\infty)$  is continuous,  $g : (0, 1) \rightarrow [0, +\infty)$  is continuous and  $g(t)$  is singular at the points  $t = 0$  and  $t = 1$  with  $0 < \int_0^1 D(s)g(s)ds \leq 2.7427 < +\infty$ . In addition, we can easily obtain that

$$\begin{aligned} \liminf_{\substack{u \rightarrow 0^+ \\ v \rightarrow 0^+}} \frac{f(t, u, v)}{u+v} &= \liminf_{\substack{u \rightarrow 0^+ \\ v \rightarrow 0^+}} \frac{(u+v)^{-\frac{1}{4}} + v^{-\frac{1}{8}}}{u+v} = +\infty, \\ \limsup_{\substack{u+v \rightarrow +\infty \\ v \rightarrow +\infty}} \frac{f(t, u, v)}{v} &= \limsup_{\substack{u+v \rightarrow +\infty \\ v \rightarrow +\infty}} \frac{(u+v)^{-\frac{1}{4}} + v^{-\frac{1}{8}}}{v} = 0, \end{aligned}$$

where  $u(t) = y(t)$ ,  $v(t) = D_{0+}^{\frac{1}{4}} y(t)$ , then  $u(t) = I_{0+}^{\frac{1}{4}} v(t)$ . This means that

$$\limsup_{\substack{u+v \rightarrow +\infty \\ v \rightarrow +\infty}} \frac{f(t, u, v)}{v} < \lambda_1 < \liminf_{\substack{u \rightarrow 0^+ \\ v \rightarrow 0^+}} \frac{f(t, u, v)}{u+v}.$$

Therefore, we prove that the problem satisfies all the assumptions of Theorem 3.1. Consequently, Theorem 3.1 guarantees that equation (4.1) has at least a solution.

## 5. Conclusion

In this paper, we obtained several sufficient conditions for the existence of positive solutions for nonlinear fractional differential equation involving multi-point boundary conditions. Our results will be a useful contribution to the existing literature on the topic of fractional-order nonlocal differential equations. The results of the existence are demonstrated on a relevant example.

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