# Positive Periodic Solutions for First-Order Nonlinear Neutral Differential Equations

#### T. Candan<sup>†</sup>

**Abstract** We consider a first-order nonlinear neutral differential equation. By employing Krasnoselskii's fixed point theorem, we provide several new criteria for the existence of positive periodic solutions to this equation. The theorems we have formulated are exemplified through a specific example.

**Keywords** Fixed point, neutral equations, positive periodic solution, first-order

MSC(2010) 34C25, 34K13.

#### 1. Introduction

In this current study, we explore the existence of positive  $\omega$ -periodic solutions for a first-order neutral differential equation given by

$$(a(t)x(t))' = -b(t)x(t) + c(t)x'(t - h(t)) + f(t, x(t - h(t))),$$
(1.1)

where  $a \in C^1(\mathbb{R}, (0, \infty))$ ,  $b \in C(\mathbb{R}, (0, \infty))$ ,  $c \in C^1(\mathbb{R}, \mathbb{R})$ ,  $h \in C^2(\mathbb{R}, (0, \infty))$  with  $h'(t) \neq 1$  for all  $t \in [0, \omega]$ , which are  $\omega$ -periodic functions. Additionally,  $f \in C(\mathbb{R} \times \mathbb{R}, \mathbb{R})$  is an  $\omega$ -periodic function in t, and  $\omega$  is a positive constant.

In fact, neutral differential equations and periodic phenomena appear in different models from real world applications; please see, e.g., [1,7,9,13]. Our investigation builds upon the positive periodic solutions of the equation

$$x'(t) = -a(t)x(t) + c(t)x'(t - g(t)) + q(t, x(t - g(t))),$$
(1.2)

with  $0 \leqslant \frac{c(t)}{1-g'(t)} < 1$ ,  $-1 \leqslant \frac{c(t)}{1-g'(t)} \leqslant 0$ , initiated in [18]. Our study extends and generalizes the results from [18] by considering the special case when a(t)=1, leading to the equation above. This indicates that our findings not only encompass, but also offer broader insight compared to those obtained in [18], particularly for the more general equation.

In summary, our study provides generalizations and new criteria for positive periodic solutions in (1.1), complementing existing research in [2, 3, 5, 6, 8, 10–12, 14–17, 19] that explores positive periodic solutions in various types of first-order neutral differential equations. Additionally, the work in [4] focuses on positive periodic solutions to second-order neutral differential equations.

 $Email\ address:\ Tuncay. Candan@aum.edu.kw$ 

College of Engineering and Technology, American University of the Middle East, Kuwait.

<sup>&</sup>lt;sup>†</sup>The corresponding author.

### 2. Main results

Consider a function space  $\Phi_{\omega}$  consisting of  $\omega$ -periodic continuous functions equipped with the supremum norm, denoted as  $||x|| = \sup_{t \in [0,\omega]} |x(t)|$ . It is evident that the pair

$$(\Phi_{\omega}, \|\cdot\|)$$
 forms a Banach space. Let  $a_0 = \min_{t \in [0,\omega]} a(t)$  and  $a_1 = \max_{t \in [0,\omega]} a(t)$ .

**Theorem 2.1.** Let  $0 \le c_0 \le \frac{c(t)}{a(t)(1-h'(t))} \le c_1 < 1$ . Furthermore, assume that there exist positive constants  $m_0$  and  $m_1$  with  $m_0 < m_1$  such that

$$(1 - c_0)a_1 m_0 \leqslant \frac{a(t)}{b(t)} \Big( f(t, x) - r(t)x \Big) \leqslant (1 - c_1)a_0 m_1 \tag{2.1}$$

for all  $t \in [0, \omega], x \in [m_0, m_1], where$ 

$$r(t) = \frac{\left(c'(t) + \frac{b(t)}{a(t)}c(t)\right)\left(1 - h'(t)\right) + h''(t)c(t)}{\left(1 - h'(t)\right)^2}.$$

Then, (1.1) has at least one positive  $\omega$ -periodic solution  $x(t) \in [m_0, m_1]$ .

**Proof.** Clearly, obtaining an  $\omega$ -periodic solution of (1.1) is equivalent to finding an  $\omega$ -periodic solution for the following integral equation

$$x(t) = \frac{1}{a(t)} \left[ \frac{c(t)}{1 - h'(t)} x(t - h(t)) + \int_{t}^{t+\omega} G(t, s) \left[ f(s, x(s - h(s))) - r(s) x(s - h(s)) \right] ds \right],$$

where

$$G(t,s) = \frac{e^{\int_t^s \frac{b(u)}{a(u)} du}}{e^{\int_0^\omega \frac{b(u)}{a(u)} du} - 1}.$$

Consider the set  $\Phi = \{x \in \Phi_{\omega} : m_0 \leq x(t) \leq m_1, t \in [0, \omega]\}$ , which forms a bounded closed and convex subset of  $\Phi_{\omega}$ . Now, define the operators  $\mathcal{T}, \mathcal{S} : \Phi \to \Phi_{\omega}$  as follows:

$$(\mathcal{T}x)(t) = \frac{c(t)}{a(t)(1 - h'(t))}x(t - h(t))$$
(2.2)

and

$$(Sx)(t) = \frac{1}{a(t)} \int_{t}^{t+\omega} G(t,s) \Big[ f(s, x(s-h(s))) - r(s)x(s-h(s)) \Big] ds.$$
 (2.3)

For every  $x \in \Phi$  and  $t \in \mathbb{R}$ , deducing from (2.2) and (2.3), it becomes evident that

$$(\mathcal{T}x)(t+\omega) = \frac{c(t+\omega)}{a(t+\omega)(1-h'(t+\omega))}x(t+\omega-h(t+\omega))$$
$$= \frac{c(t)}{a(t)(1-h'(t))}x(t-h(t))$$
$$= (\mathcal{T}x)(t)$$

940 T. Candan

and

$$(\mathcal{S}x)(t+\omega) = \frac{1}{a(t+\omega)} \int_{t+\omega}^{t+2\omega} G(t+\omega,s) \Big[ f(s,x(s-h(s))) - r(s)x(s-h(s)) \Big] ds$$

$$= \frac{1}{a(t+\omega)} \int_{t}^{t+\omega} G(t+\omega,v+\omega) \Big[ f(v+\omega,x(v+\omega-h(v+\omega)))$$

$$- r(v+\omega)x(v+\omega-h(v+\omega)) \Big] dv$$

$$= \frac{1}{a(t)} \int_{t}^{t+\omega} G(t,v) \Big[ f(v,x(v-h(v))) - r(v)x(v-h(v)) \Big] dv$$

$$= (\mathcal{S}x)(t).$$

This indicates that  $\mathcal{T}(\Phi) \subset \Phi_{\omega}$  and  $\mathcal{S}(\Phi) \subset \Phi_{\omega}$ . Next, we demonstrate that  $\mathcal{T}x + \mathcal{S}y \in \Phi$  for all  $x, y \in \Phi$  and  $t \in \mathbb{R}$ . Utilizing (2.1), (2.2), and (2.3), we obtain

$$(\mathcal{T}x)(t) + (\mathcal{S}y)(t) = \frac{c(t)}{a(t)(1 - h'(t))} x(t - h(t))$$

$$+ \frac{1}{a(t)} \int_{t}^{t+\omega} G(t, s) \Big[ f(s, y(s - h(s))) - r(s)y(s - h(s)) \Big] ds$$

$$\leqslant c_{1}m_{1} + \frac{1}{a_{0}} \int_{t}^{t+\omega} G(t, s) \frac{b(s)}{a(s)} \Big[ \frac{a(s)}{b(s)} \Big( f(s, y(s - h(s))) - r(s)y(s - h(s)) \Big) \Big] ds$$

$$\leqslant c_{1}m_{1} + \frac{1}{a_{0}} (1 - c_{1})a_{0}m_{1} \int_{t}^{t+\omega} G(t, s) \frac{b(s)}{a(s)} ds$$

$$= m_{1}$$

and

$$(\mathcal{T}x)(t) + (\mathcal{S}y)(t) = \frac{c(t)}{a(t)(1 - h'(t))}x(t - h(t)) + \frac{1}{a(t)} \int_{t}^{t+\omega} G(t,s) \Big[ f(s,y(s - h(s))) - r(s)y(s - h(s)) \Big] ds \geqslant c_{0}m_{0} + \frac{1}{a_{1}} \int_{t}^{t+\omega} G(t,s) \frac{b(s)}{a(s)} \Big[ \frac{a(s)}{b(s)} \Big( f(s,y(s - h(s))) - r(s)y(s - h(s)) \Big) \Big] ds \geqslant c_{0}m_{0} + \frac{1}{a_{1}} (1 - c_{0})a_{1}m_{0} \int_{t}^{t+\omega} G(t,s) \frac{b(s)}{a(s)} ds = m_{0}.$$

This indicates that  $\mathcal{T}x + \mathcal{S}y \in \Phi$  for all  $x, y \in \Phi$ . Now, we aim to demonstrate that  $\mathcal{T}$  is a contraction mapping on  $\Phi$ . For  $x, y \in \Phi$ , we observe

$$|(\mathcal{T}x)(t) - (\mathcal{T}y)(t)| = \left| \frac{c(t)}{a(t)(1 - h'(t))} x(t - h(t)) - \frac{c(t)}{a(t)(1 - h'(t))} y(t - h(t)) \right|$$

$$\leqslant \frac{c(t)}{a(t)(1 - h'(t))} \left| x(t - h(t)) - y(t - h(t)) \right|.$$

By considering the supremum norm on both sides, it is evident that

$$\|\mathcal{T}x - \mathcal{T}y\| \leqslant c_1 \|x - y\|.$$

This establishes that  $\mathcal{T}$  is a contraction mapping. We will illustrate that  $\mathcal{S}$  is continuous. Let  $\{x_n\} \in \Phi$  be a convergent sequence of elements such that  $x_n(t) \to x(t)$  as  $n \to \infty$ . As  $\Phi$  is closed, it implies  $x \in \Phi$ . For  $t \in [0, \omega]$ , we have

$$|(Sx_n)(t) - (Sx)(t)| = \left| \frac{1}{a(t)} \int_t^{t+\omega} G(t,s) \left[ f(s, x_n(s - h(s))) - r(s) x_n(s - h(s)) \right] ds \right|$$

$$- \frac{1}{a(t)} \int_t^{t+\omega} G(t,s) \left[ f(s, x(s - h(s))) - r(s) x(s - h(s)) \right] ds$$

$$\leq \frac{1}{a_0} \int_t^{t+\omega} G(t,s) |r(s)| \left| x_n(s - h(s)) - x(s - h(s)) \right| ds$$

$$+ \frac{1}{a_0} \int_t^{t+\omega} G(t,s) \left| f(s, x_n(s - h(s))) - f(s, x(s - h(s))) \right| ds.$$

By the continuity of f and by the Lebesgue dominated convergence theorem, it follows that

$$\lim_{n \to \infty} \|(\mathcal{S}x_n) - (\mathcal{S}x)\| = 0.$$

This indicates that S is continuous. Now, we show that the family of functions  $\{Sx : x \in \Phi\}$  is uniformly bounded and equicontinuous on  $[0, \omega]$ . We observe from (2.1) that

$$\begin{aligned} |(\mathcal{S}x)(t)| &= \left| \frac{1}{a(t)} \int_{t}^{t+\omega} G(t,s) \left[ f(s,x(s-h(s))) - r(s)x(s-h(s)) \right] ds \right| \\ &\leq \left| \frac{1}{a(t)} \int_{t}^{t+\omega} G(t,s) \frac{b(s)}{a(s)} \left[ \frac{a(s)}{b(s)} \left( f(s,x(s-h(s))) - r(s)x(s-h(s)) \right) \right] ds \right| \\ &\leq \frac{1}{a_0} (1-c_1) a_0 m_1 \int_{t}^{t+\omega} G(t,s) \frac{b(s)}{a(s)} ds \\ &= (1-c_1) m_1 \end{aligned}$$

and it follows that

$$\|\mathcal{S}x\| \leqslant (1-c_1)m_1.$$

Moreover, by using (2.1), we derive

$$\begin{split} |(\mathcal{S}x)'(t)| &= \left| \frac{d}{dt} \left[ \frac{1}{a(t)} \int_{t}^{t+\omega} G(t,s) \left[ f(s,x(s-h(s))) - r(s)x(s-h(s)) \right] ds \right| \\ &\leq \left| \frac{d}{dt} \left[ \frac{1}{a(t)} \right] a(t) (\mathcal{S}x)(t) + \frac{1}{a(t)} \left[ G(t,t+\omega) \left[ f(t,x(t-h(t))) - r(t)x(t-h(t)) \right] \right] \\ &- G(t,t) \left[ f(t,x(t-h(t))) - r(t)x(t-h(t)) \right] \right] - b(t) (\mathcal{S}x)(t) \\ &\leq \left| \frac{-a'(t)}{a(t)} (\mathcal{S}x)(t) \right| \end{split}$$

942 T. Candan

$$+ \frac{1}{a(t)} \left[ \frac{b(t)}{a(t)} \left[ \frac{a(t)}{b(t)} \left( f(t, x(t - h(t))) - r(t)x(t - h(t)) \right) \right] - b(t)(\mathcal{S}x)(t) \right]$$

$$\leq \frac{1}{a_0} \left[ \|a'\| \|\mathcal{S}x\| + \|b\| (1 - c_1)m_1 + \|b\| \|\mathcal{S}x\| \right]$$

$$\leq \frac{1}{a_0} \left[ \|a'\| + 2\|b\| \right] (1 - c_1)m_1.$$

Thus,  $\{Sx : x \in \Phi\}$  is uniformly bounded and equicontinuous on  $[0, \omega]$ . Consequently,  $S\Phi$  is relatively compact. These observations lead us to the conclusion that S is completely continuous. Applying the fixed-point theorem of Krasnoselskii, we infer the existence of  $x \in \Phi$  such that  $\mathcal{T}x + Sx = x$ . This implies that x(t) is a positive  $\omega$ -periodic solution of (1.1).

**Theorem 2.2.** Let  $-1 < c_0 \leqslant \frac{c(t)}{a(t)(1-h'(t))} \leqslant c_1 \leqslant 0$ . Furthermore, assume that there exist positive constants  $m_0$  and  $m_1$  with  $m_0 < m_1$  such that

$$(m_0 - c_0 m_1)a_1 \le \frac{a(t)}{b(t)} \Big( f(t, x) - r(t)x \Big) \le (m_1 - c_1 m_0)a_0$$
 (2.4)

for all  $t \in [0, \omega]$ ,  $x \in [m_0, m_1]$ , where

$$r(t) = \frac{\left(c'(t) + \frac{b(t)}{a(t)}c(t)\right)\left(1 - h'(t)\right) + h''(t)c(t)}{\left(1 - h'(t)\right)^2}, \quad t \in [0, \omega].$$

Then, (1.1) has at least one positive  $\omega$ -periodic solution  $x(t) \in [m_0, m_1]$ .

**Proof.** We define  $\Phi$ , G(t,s),  $\mathcal{T}$ , and  $\mathcal{S}$  as outlined in the proof of Theorem 2.1. It is evident from the proof of Theorem 2.1 that  $\mathcal{T}(\Phi) \subset \Phi_{\omega}$  and  $\mathcal{S}(\Phi) \subset \Phi_{\omega}$ . Next, we demonstrate that  $\mathcal{T}x + \mathcal{S}y \in \Phi$  for all  $x, y \in \Phi$  and  $t \in \mathbb{R}$ . By utilizing (2.2), (2.3), and (2.4), we obtain

$$(\mathcal{T}x)(t) + (\mathcal{S}y)(t) = \frac{c(t)}{a(t)(1 - h'(t))}x(t - h(t))$$

$$+ \frac{1}{a(t)} \int_{t}^{t+\omega} G(t, s) \Big[ f(s, y(s - h(s))) - r(s)y(s - h(s)) \Big] ds$$

$$\leqslant c_{1}m_{0} + \frac{1}{a_{0}} \int_{t}^{t+\omega} G(t, s) \frac{b(s)}{a(s)} \Big[ \frac{a(s)}{b(s)} \Big( f(s, y(s - h(s))) - r(s)y(s - h(s)) \Big) \Big] ds$$

$$\leqslant c_{1}m_{0} + \frac{1}{a_{0}} (m_{1} - c_{1}m_{0}) a_{0} \int_{t}^{t+\omega} G(t, s) \frac{b(s)}{a(s)} ds$$

$$= m_{1}$$

and

$$(\mathcal{T}x)(t) + (\mathcal{S}y)(t) = \frac{c(t)}{a(t)(1 - h'(t))}x(t - h(t)) + \frac{1}{a(t)} \int_{t}^{t+\omega} G(t, s) \Big[ f(s, y(s - h(s))) - r(s)y(s - h(s)) \Big] ds$$

$$\geq c_0 m_1 + \frac{1}{a_1} \int_t^{t+\omega} G(t,s) \frac{b(s)}{a(s)} \left[ \frac{a(s)}{b(s)} \left( f(s, y(s-h(s))) - r(s)y(s-h(s)) \right) \right] ds$$

$$\geq c_0 m_1 + \frac{1}{a_1} (m_0 - c_0 m_1) a_1 \int_t^{t+\omega} G(t,s) \frac{b(s)}{a(s)} ds$$

$$= m_0.$$

This results in  $\mathcal{T}x + \mathcal{S}y \in \Phi$  for all  $x, y \in \Phi$ . Now, let's establish that  $\mathcal{T}$  is a contraction mapping on  $\Phi$ . For  $x, y \in \Phi$ , we observe

$$|(\mathcal{T}x)(t) - (\mathcal{T}y)(t)|| = \left| \frac{c(t)}{a(t)(1 - h'(t))} x(t - h(t)) - \frac{c(t)}{a(t)(1 - h'(t))} y(t - h(t)) \right|$$

$$\leq \frac{-c(t)}{a(t)(1 - h'(t))} \left| x(t - h(t)) - y(t - h(t)) \right|.$$

Taking the supremum norm on both sides, we get

$$\|\mathcal{T}x - \mathcal{T}y\| \leqslant -c_0\|x - y\|.$$

Therefore,  $\mathcal{T}$  is a contraction mapping. As the remainder of the proof parallels that of Theorem 2.1, it will be omitted to avoid redundancy.

**Example 2.1.** Consider the first-order neutral differential equation

$$(2e^{\frac{\cos(t)}{10}}x(t))' = -10e^{\frac{11\cos(t)}{10}}x(t) + e^{-\frac{\cos(t)}{5}}x'(t - e^{\frac{\cos(t)}{5}}) + e^{1 - 0.16\sin(t) + 0.8\cos(t)} \left(12 + 2x(t - e^{\frac{\cos(t)}{5}})\right).$$
(2.5)

It can be seen that (2.5) is of the form (1.1) with  $a(t) = 2e^{\frac{\cos(t)}{10}}$ ,  $b(t) = 10e^{\frac{11\cos(t)}{10}}$ ,  $c(t) = e^{-\frac{\cos(t)}{5}}$ ,  $h(t) = e^{\frac{\cos(t)}{5}}$ ,  $\omega = 2\pi$ ,  $f(t,x) = e^{1-0.16\sin(t)+0.8\cos(t)}(12+2x)$ ,  $a_0 = \min_{t \in [0,\omega]} a(t) = 1.8090$ , and  $a_1 = \max_{t \in [0,\omega]} a(t) = 2.2103$ . After straightforward calculation, we can obtain

$$c'(t) = \frac{\sin(t)}{5}e^{-\frac{\cos(t)}{5}}, \qquad h'(t) = -\frac{\sin(t)}{5}e^{\frac{\cos(t)}{5}},$$
 
$$h''(t) = e^{\frac{\cos(t)}{5}} \left[ \frac{-\cos(t)}{5} + \frac{\sin^2(t)}{25} \right],$$
 
$$r(t) = \frac{\left(c'(t) + \frac{b(t)}{a(t)}c(t)\right)\left(1 - h'(t)\right) + h''(t)c(t)}{\left(1 - h'(t)\right)^2}$$
 
$$= \frac{\left(\frac{\sin(t)}{5} + 5e^{\cos(t)}\right)\left(e^{-\frac{\cos(t)}{5}} + \frac{\sin(t)}{5}\right) + \left(\frac{-\cos(t)}{5} + \frac{\sin^2(t)}{25}\right)}{\left(1 + \frac{\sin(t)}{5}e^{\frac{\cos(t)}{5}}\right)^2},$$

$$0 \leqslant 0.3444 = c_0 \leqslant \frac{c(t)}{a(t)(1 - h'(t))} = \frac{e^{-\frac{\cos(t)}{5}}}{2e^{\frac{\cos(t)}{10}} \left(1 + \frac{\sin(t)}{5}e^{\frac{\cos(t)}{5}}\right)} \leqslant c_1 = 0.7083 < 1,$$

944 T. Candan

$$(1-c_0)a_1m_0 = (1-0.3444)(2.2103)2 = 2.8981$$
 and  $(1-c_1)a_0m_1 = (1-0.7083)(1.8090)21 = 11.0814$ . Therefore,

$$2.8981 = (1 - c_0)a_1m_0 < 5.1345 \leqslant \frac{a(t)}{b(t)} \Big( f(t, x) - r(t)x \Big) \leqslant 9.6196$$
$$< (1 - c_1)a_0m_1 = 11.0814.$$

It shows that the conditions of Theorem 2.1 are satisfied when  $m_0 = 2$  and  $m_1 = 21$ . Thus (2.5) has at least one  $2\pi$ -periodic positive solution x(t) satisfying  $2 \le x(t) \le 21$ .

## References

- [1] E. Beretta, F. Solimano and Y. Takeuchi, A mathematical model for drug administration by using the phagocytosis of red blood cells, J Math Biol., 35 (1996), 1-19.
- [2] T. Candan, Existence of positive periodic solutions of first order neutral differential equations with variable coefficients, Appl. Math. Lett., 52 (2016), 142-148
- [3] T. Candan, Existence of positive periodic solutions of first order neutral differential equations, Math. Methods Appl. Sci., 40(1) (2017), 205-209.
- [4] T. Candan, Existence of positive periodic solution of second-order neutral differential equations, Turkish J. Math., 42(3) (2018), 797-806.
- [5] T. Candan, Existence of positive periodic solutions of first order neutral differential equations, Konuralp J. Math., 11(1) (2023), 15-19.
- [6] T. Candan, Existence results for positive periodic solutions to first-order neutral differential equations, Mediterr. J. Math., 21(3) (2024), Paper No. 98, 14 pp.
- [7] F. D. Chen, Positive periodic solutions of neutral Lotka-Volterra system with feedback control, Appl. Math. Comput., 162 (2005), 1279-1302.
- [8] Z. Cheng, L. Lv and J. Liu, Positive periodic solution of first-order neutral differential equation with infinite distributed delay and applications, AIMS Math., 5(6) (2020), 7372-7386.
- K-S. Chiu and T. Li, Oscillatory and periodic solutions of differential equations with piecewise constant generalized mixed arguments, Math. Nachr., 292(10) (2019), 2153-2164.
- [10] M. Gözen, On the existence and uniqueness of positive periodic solutions of neutral differential equations, Journal of Nonlinear and Variational Analysis, 7(3) (2023).
- [11] J. R. Graef and L. Kong, *Periodic solutions of first order functional differential equations*, Appl. Math. Lett., 24 (2011), 1981-1985.
- [12] A. Guerfi and A. Ardjouni, Positive periodic solutions of a first order neutral dynamic equation on periodic time scales, Adv. Stud. Euro-Tbil. Math. J., 16 (3) (2023), 77-87.
- [13] T. Li and Y. V. Rogovchenko, On the asymptotic behavior of solutions to a class of third-order nonlinear neutral differential equations, Appl. Math. Lett., 105 (2020), Art. 106293, pp. 1-7.

- [14] Z. Li and X. Wang, Existence of positive periodic solutions for neutral functional differential equations, Electron. J. Differential Equations, 34 (2006), 8 pp.
- [15] Z. Liu, X. Li, S. M. Kang and Y. C. Kwun, Positive periodic solutions for first-order neutral functional differential equations with periodic delays, Abstr. Appl. Anal., (2012), 185692, 12 pp.
- [16] Y. Luo, W. Wang and J. Shen, Existence of positive periodic solutions for two kinds of neutral functional differential equations, Appl. Math. Lett., 21 (2008), 581-587.
- [17] M. B. Mesmouli, A. Ardjouni and A. Djoudi, Positive periodic solutions for first-order nonlinear neutral functional differential equations with periodic delay, Transylv. J. Math. Mech., 6 (2014), 151-162.
- [18] Y. N. Raffoul, Existence of positive periodic solutions in neutral nonlinear equations with functional delay, Rocky Mountain J. Math., 42(6) (2012), 1983-1993.
- [19] S. Zhu and B. Du, Positive Periodic Solutions for a First-Order Nonlinear Neutral Differential Equation with Impulses on Time Scales, Symmetry, 15(5) (2023), 1072.