

## ASYMPTOTIC BEHAVIOR OF SOLUTIONS FOR THE BELOUSOV-ZHABOTINSKII REACTION DIFFUSION SYSTEM

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### Abstract

The present paper characterizes the asymptotic behavior of the time-dependent solution of the coupled Belousov-Zhabotinskii reaction diffusion equations in relation to the steady-state solutions of the corresponding boundary value problem. This characterization leads to an explicit relationship among the various physical constants and the boundary and initial functions.

### 1. Introduction

In some chemical reaction problems, a simplified model for the concentration densities  $u \equiv u(t, x)$ ,  $v \equiv v(t, x)$  of two reactants, such as bromous acid and bromide ion, is given by a coupled system of reaction diffusion equations in the form

$$\begin{aligned} u_t - D_1 \nabla^2 u &= u(a - bu - cv) \\ v_t - D_2 \nabla^2 v &= -c_1 uv \end{aligned} \quad (t > 0, x \in \Omega) \quad (1.1)$$

Where  $D_1, D_2, a, b, c$  and  $c_1$  are positive constants and  $\Omega$  is the reaction-diffusion medium. The coupled system is often referred to as the Belousov-Zhabotinskii chemical reaction equations and has been given considerable attention in recent years (cf. [1-5, 10]). Much discussion of Eq. (1.1) is devoted to the traveling wave solution in the one-dimensional spatial domain  $\Omega \equiv \mathbb{R}^1$ . When  $\Omega$  is a general bounded domain in  $\mathbb{R}^n$ , Eq. (1.1) is supplemented by a boundary condition in the form

$$\begin{aligned} \alpha(x) \partial u / \partial \nu + \beta(x) u &= 0 \\ \alpha(x) \partial v / \partial \nu + \beta(x) v &= 0 \end{aligned} \quad (t > 0, x \in \partial \Omega) \quad (1.2)$$

together with the initial condition

$$u(0, x) = u_0(x), \quad v(0, x) = v_0(x) \quad (x \in \Omega) \quad (1.3)$$

where  $\alpha \geq 0, \beta \geq 0$  with  $\alpha + \beta > 0$ ,  $\partial / \partial \nu$  is the outward normal derivative on  $\partial \Omega$ , and  $u_0 \geq 0, v_0 \geq 0$  in  $\Omega$ . It is assumed that the functions in (1.2) (1.3) and the domain  $\Omega$  are smooth and  $\beta(x)$  is not identically zero (see [5] for the case  $\beta(x) \equiv 0$ ).

It has been shown in [5] that for any nonnegative initial function  $u_0, v_0$ , problem (1.1) - (1.3) has a unique nonnegative solution  $(u, v)$ . The aim of this paper is to give a more precise description about the asymptotic behavior of the solution  $(u, v)$  in relation to the steady-state solutions of the corresponding boundary-value problem

$$-D_1 \nabla^2 u = u(a - bu - cv) \quad (t > 0, x \in \Omega) \quad (1.4)$$

$$\begin{aligned} -D_2 \nabla^2 v &= -c_1 uv \\ \alpha(x) \partial u / \partial \nu + \beta(x) u &= 0 \\ \alpha(x) \partial v / \partial \nu + \beta(x) v &= 0 \end{aligned} \quad (t > 0, x \in \partial \Omega) \quad (1.5)$$

Since problem (1.4) (1.5) has the trivial solution  $(0, 0)$  it is interesting to know when it has a nontrivial solution, and whether and when the time dependent solution  $(u, v)$  converges to the nontrivial solution. Our main results characterize the asymptotic behavior of the solution  $(u, v)$  in terms of the various physical constants in (1.1) as

well as the effect of the boundary and initial conditions (1.2) (1.3).

## 2. The Main Results

The characterization of the existence of a nontrivial steady-state solution and its relation to the time-dependent solution is based on the smallest eigenvalue  $\lambda_0$  and its corresponding eigenfunction  $\varphi(x)$  of the eigenvalue problem

$$\nabla^2 \varphi + \lambda \varphi = 0 \quad \text{in } \Omega, \quad B[\varphi] = 0 \quad \text{on } \partial\Omega \quad (2.1)$$

where  $B[w] \equiv \alpha(x) \partial w / \partial \nu + \beta(x) w$  for any function  $w$ . It is well-known that  $\lambda_0 > 0$  and  $\varphi(x) > 0$  in  $\Omega$ . When  $\alpha(x) > 0$  the maximum principle implies that  $\varphi(x) > 0$  on  $\bar{\Omega}$ . We normalize  $\varphi$  so that  $\max \varphi(x) = 1$  on  $\bar{\Omega}$ . The following existence result for the scalar boundary value problem

$$-D_1 \nabla^2 U = U(a - bU) \quad \text{in } \Omega, \quad B[U] = 0 \quad \text{on } \partial\Omega \quad (2.2)$$

is well-known.

**Lemma 2.1.** *Problem (2.2) has only the trivial solution  $U=0$  when  $a \leq \lambda_0 D_1$ ; and it has a unique positive solution  $U_s(x)$  when  $a > \lambda_0 D_1$ .*

A proof of the above lemma can be found in [9, p. 1174]. Based on the solution  $U_s$  of problem (2.2) we state our main results in the following two theorems.

**Theorem 1.** *The steady-state problem (1.4) (1.5) has only the trivial solution  $(0, 0)$  when  $a \leq \lambda_0 D_1$ ; and it has exactly two solutions  $(0, 0)$  and  $(U_s, 0)$  when  $a > \lambda_0 D_1$ , where  $U_s$  is the unique positive solution of (2.2).*

**Theorem 2.** *Let  $(u, v)$  be the nonnegative solution of (1.1) - (1.3) with any  $(u_0, v_0) \geq (0, 0)$  and let  $U_s$  be the positive solution of problem (2.2). Then*

$$\lim_{t \rightarrow \infty} (u(t, x), v(t, x)) = (0, 0) \quad (2.3)$$

when  $a \leq \lambda_0 D_1$  or when  $u_0(x) \equiv 0$ , and

$$\lim_{t \rightarrow \infty} (u(t, x), v(t, x)) = (U_s(x), 0) \quad (2.4)$$

when  $a > \lambda_0 D_1$  and  $u_0(x) \geq \varepsilon \varphi(x)$ , where  $\varepsilon > 0$  can be arbitrarily small.

**Remark 2.1.** When  $a > \lambda_0 D_1$  the conclusion in (2.4) also hold for any  $U_0(x) \not\equiv 0$  provided that  $\alpha(x) > 0$ . For in this situation the maximum principle implies that  $u(t, x) > 0$  on  $R^+ \times \bar{\Omega}$ . By considering problem (1.1) - (1.3) with the initial functions  $u(t_1, x), v(t_1, x)$  in the domain  $[t_1, \infty) \times \Omega$  for a fixed  $t_1 > 0$ , the requirement  $u(t_1, x) \geq \varepsilon \varphi(x)$  for some  $\varepsilon > 0$  is clearly satisfied. It follows from the uniqueness property of the solution  $(u, v)$  that (2.4) holds.

## 3. Proof of the Main Theorems

**Proof of Theorem 1.** Let  $(U_s(x), V_s(x))$  be any nonnegative solution of (1.4) (1.5). Multiplying both equations in (1.4) by  $\varphi(x)$  and integrating over  $\Omega$  yield

$$-D_1 \int_{\Omega} \varphi \nabla^2 U_s dx = \int_{\Omega} \varphi U_s (a - bU_s - cV_s) dx$$

$$-D_2 \int_{\Omega} \varphi \nabla^2 V_s dx = -c_1 \int_{\Omega} \varphi U_s V_s dx$$

By applying the Green's theorem and using the boundary condition (1.5) the above equations become

$$(\lambda_0 D_1 - a) \int_{\Omega} \varphi U_s dx = - \int_{\Omega} (b\varphi U_s^2 + c\varphi U_s V_s) dx \quad (3.1)$$

$$\lambda_0 D_2 \int_{\Omega} \varphi V_s dx = -c_1 \int_{\Omega} \varphi U_s V_s dx \leq 0$$

Since  $\varphi(x) > 0$  in  $\Omega$ , the second relation in (3.1) implies that  $V_s(x) = 0$  in  $\Omega$ .