

## Symmetry and Uniqueness of Solutions of an Integral System

ZHANG Zhengce<sup>1,\*</sup> and JIANG Minji<sup>2</sup>

<sup>1</sup> College of Science, Xi'an Jiaotong University, Xi'an 710049, P. R. China.

<sup>2</sup> Beijing Aerospace Control Center, Beijing 5130-109, P. R. China.

Received 27 September 2010; Accepted 25 May 2011

---

**Abstract.** In this paper, we study the positive solutions for a class of integral systems and prove that all the solutions are radially symmetric and monotonically decreasing about some point. Moreover, we also obtain the uniqueness result for a special case. We use a new type of moving plane method introduced by Chen-Li-Ou [1]. Our new ingredient is the use of Hardy-Littlewood-Sobolev inequality instead of Maximum Principle.

**AMS Subject Classifications:** 35J65, 35J25, 35B50

**Chinese Library Classifications:** O175.5

**Key Words:** Radial symmetry; uniqueness; integral system; moving plane method.

---

### 1 Introduction

In this paper, we study positive solutions of the following system of integral equations in  $\mathbb{R}^N$

$$\begin{cases} u(x) = \int_{\mathbb{R}^N} \frac{u(y)^k + v(y)^p}{|x-y|^{N-\alpha}} dy \\ v(x) = \int_{\mathbb{R}^N} \frac{u(y)^q + v(y)^t}{|x-y|^{N-\alpha}} dy \end{cases} \quad (1.1)$$

with  $k = p = q = t = (N + \alpha) / (N - \alpha)$  and  $0 < \alpha < N$ . Under the local integrability conditions  $u \in L_{loc}^{2N/(N-\alpha)}(\mathbb{R}^N)$  and  $v \in L_{loc}^{2N/(N-\alpha)}(\mathbb{R}^N)$ , we first prove that all the solutions are radially symmetric and monotonically decreasing about some point, then we also obtain the uniqueness result for the special case  $\alpha = 2$ . We shall use a new type of moving plane method introduced by Chen-Li-Ou, which technically uses the Hardy-Littlewood-Sobolev inequality instead of Maximum Principle.

---

\*Corresponding author. Email addresses: zhangzc@mail.xjtu.edu.cn (Z. Zhang), 2003jmj@163.com (M. Jiang)

The integral system (1.1) is closely related to the system of PDEs

$$\begin{cases} (-\Delta)^{\alpha/2}u = u^k + v^p, \\ (-\Delta)^{\alpha/2}v = u^q + v^t, \end{cases} \quad u, v > 0 \text{ in } \mathbb{R}^N. \tag{1.2}$$

In fact, every positive smooth solution of PDE (1.2) multiplied by a constant satisfies (1.1). This can be easily verified as in the proof of Theorem 4.5 in [1]. We also refer this equivalence to [2] for a system with  $\alpha = 2$ . In fact, in (1.2), we define the positive solution of (1.2) in the distribution sense, i.e.,  $u, v \in H^{\alpha/2}(\mathbb{R}^N)$  satisfies, for any  $\phi \in C_0^\infty$  and  $\phi \geq 0$ ,

$$\begin{cases} \int_{\mathbb{R}^N} (-\Delta)^{\alpha/4}u(-\Delta)^{\alpha/4}\phi dx = \int_{\mathbb{R}^N} [u^k(x) + v^p(x)]\phi(x)dx, \\ \int_{\mathbb{R}^N} (-\Delta)^{\alpha/4}v(-\Delta)^{\alpha/4}\phi dx = \int_{\mathbb{R}^N} [u^q(x) + v^t(x)]\phi(x)dx, \end{cases} \tag{1.3}$$

where

$$\int_{\mathbb{R}^N} (-\Delta)^{\alpha/4}u(-\Delta)^{\alpha/4}\phi dx \quad \text{and} \quad \int_{\mathbb{R}^N} (-\Delta)^{\alpha/4}v(-\Delta)^{\alpha/4}\phi dx$$

are defined by the Fourier transform

$$\int_{\mathbb{R}^N} |\xi|^\alpha \widehat{u}(\xi) \widehat{\phi}(\xi) d\xi \quad \text{and} \quad \int_{\mathbb{R}^N} |\xi|^\alpha \widehat{v}(\xi) \widehat{\phi}(\xi) d\xi.$$

Here,  $\widehat{u}, \widehat{v}$  and  $\widehat{\phi}$  are the Fourier transforms of  $u, v$  and  $\phi$ , respectively. By taking limits, one can see that (1.3) is also true for any  $\phi \in H^{\alpha/2}$ .

Since we shall use Hardy-Littlewood-Sobolev inequality to prove radial symmetry and monotonicity of our solutions, we begin by recalling the well-known Hardy-Littlewood-Sobolev inequality. Let  $\lambda, s, r$  be real numbers satisfying  $0 < \alpha < N, r, s > 1$ , and  $\|f\|_p$  be the  $L^p(\mathbb{R}^N)$  norm of the function  $f$ . We shall write by  $\|f\|_{L^p(\Omega)}$  the  $L^p$  norm of the function  $f$  on the domain  $\Omega$ . Then the classical Hardy-Littlewood-Sobolev inequality states that

$$\int_{\mathbb{R}^N} \int_{\mathbb{R}^N} \frac{f(x)g(y)}{|x-y|^{N-\alpha}} dx dy \leq C \|f\|_r \|g\|_s \tag{1.4}$$

for any  $f \in L^r(\mathbb{R}^N), g \in L^s(\mathbb{R}^N)$ , and  $1/r + 1/s = (N + \alpha)/N$ . To find the best constant  $C = C(\alpha, s, N)$  in the inequality, one can maximize the functional

$$J(f, g) = \int_{\mathbb{R}^N} \int_{\mathbb{R}^N} \frac{f(x)g(y)}{|x-y|^{N-\alpha}} dx dy \tag{1.5}$$

under the constraints  $\|f\|_r = \|g\|_s = 1$ .

There are some related works about this paper. When  $k = p = q = t = (N + \alpha)/(N - \alpha)$  and  $u(x) = v(x)$ , System (1.1) becomes the single equation

$$u(x) = \int_{\mathbb{R}^N} \frac{u(y)^{\frac{N+\alpha}{N-\alpha}}}{|x-y|^{N-\alpha}} dy, \quad u > 0 \text{ in } \mathbb{R}^N. \tag{1.6}$$