

## Optimal Regularity and Control of the Support for the Pullback Equation

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**Abstract.** Given  $f, g$  two  $C^{r,\alpha}$  either symplectic forms or volume forms on a bounded open set  $\Omega \subset \mathbb{R}^n$  with  $0 < \alpha < 1$  and  $r \geq 0$ , we give natural conditions for the existence of a map  $\varphi \in \text{Diff}^{r+1,\alpha}(\Omega; \Omega)$  satisfying

$$\varphi^*(g) = f \text{ in } \Omega \quad \text{and} \quad \text{supp}(\varphi - \text{id}) \subset \Omega.$$

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### 1 Introduction

The pullback equation  $\varphi^*(g) = f$  where  $g$  and  $f$  are both symplectic forms or both volume forms has been studied a lot. One could consult [1] for an extensive survey for the pullback equation in general. We start by giving a very brief summary for the symplectic case: Darboux [2] proved that any two symplectic forms can be pulled back locally one to another. This result has been reproved by Moser [3] using an elegant flow method. These two proofs do not produce any gain in regularity: the map  $\varphi$  is at most as regular as the data  $g$  and  $f$ . Later Bandyopadhyay-Dacorogna [4] established in particular a local existence result with optimal regularity in the Hölder spaces  $C^{r,\alpha}$ ,  $0 < \alpha < 1$ . Since the pullback equation is a system of first order PDE's, optimality means here that for  $g, f \in C^{r,\alpha}$  there exists a solution  $\varphi \in C^{r+1,\alpha}$ .

For the global case coupled with a Dirichlet condition,

$$\varphi^*(g) = f \text{ in } \Omega \quad \text{and} \quad \varphi = \text{id on } \partial\Omega, \tag{1.1}$$

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the following (quasi) optimal result has been proved in [5] (see also [4] for a slightly weaker result): given  $\omega \in C^{r,\alpha}([0,1] \times \overline{\Omega}; \Lambda^2)$  an homotopy of symplectic forms between  $g$  and  $f$  such that, for every  $t \in [0,1]$ ,

$$\omega_t - \omega_0 \text{ is exact in } \Omega \quad \text{and} \quad \omega_t \wedge \nu = \omega_0 \wedge \nu \in C^{r+1,\alpha}(\partial\Omega; \Lambda^3),$$

then there exists  $\varphi \in \text{Diff}^{r+1,\alpha}(\overline{\Omega}; \overline{\Omega})$  solving (1.1), where  $\nu$  denotes the outward unit normal of some smooth bounded open set  $\Omega$  and is identified with a 1-form. Note that, for a solution to (1.1) to exist, we necessarily have

$$g \wedge \nu = f \wedge \nu \quad \text{on } \partial\Omega.$$

Note also that the only non natural condition (whose necessity is still an open problem) is the extra regularity of  $\omega_t \wedge \nu$  on the boundary.

Concerning the case of volume forms (in which case, identifying volume forms with functions,  $\varphi^*(g) = f$  reads as the single equation  $g(\varphi) \det \nabla \varphi = f$ ) the first existence result (with no gain in regularity) for (1.1) is due to Moser [3]. Afterwards Dacorogna and Moser proved in [6] that given any  $g, f \in C^{r,\alpha}(\overline{\Omega})$  strictly positive where  $\Omega$  is a smooth connected bounded open set with

$$\int_{\Omega} g = \int_{\Omega} f, \tag{1.2}$$

there exists  $\varphi \in \text{Diff}^{r+1,\alpha}(\overline{\Omega}; \overline{\Omega})$  satisfying (1.1). Note that (1.2) is obviously necessary to solve (1.1). Other proofs of this optimal regularity result have been established in [7–9].

In this paper we give conditions to solve the pullback equation  $\varphi^*(g) = f$  in  $\Omega$  with optimal regularity in Hölder space and imposing that  $\varphi = \text{id}$  near the boundary (and not only on  $\partial\Omega$  as in (1.1)). An obvious necessary condition for this problem is then

$$\text{supp}(g - f) \subset \Omega. \tag{1.3}$$

We prove (cf. Theorems 3.1 and 3.2) that the above condition is to some extent also sufficient:

**Theorem 1.1.** (i) given  $\Omega$  a bounded open set in  $\mathbb{R}^n$  star-shaped with respect with some open ball and  $\omega$  a continuous homotopy of  $C^{r,\alpha}(\Omega; \Lambda^2)$  symplectic forms between  $g$  and  $f$  such that

$$\text{supp}(\omega_t - f) \subset \Omega \quad \text{for every } t \in [0,1],$$

there exists  $\varphi \in \text{Diff}^{r+1,\alpha}(\Omega; \Omega)$  verifying

$$\varphi^*(g) = f \text{ in } \Omega \quad \text{and} \quad \text{supp}(\varphi - \text{id}) \subset \Omega. \tag{1.4}$$

(ii) given  $g, f$  two non vanishing  $C^{r,\alpha}(\Omega)$  functions in some bounded connected open set  $\Omega$  verifying (1.2) and (1.3), there exists  $\varphi \in \text{Diff}^{r+1,\alpha}(\Omega; \Omega)$  verifying (1.4).