

THE GLOBAL SOLUTIONS OF A NONLINEAR SYSTEM OF EQUATIONS OF CHANGING TYPE*

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Abstract In this paper, the global existence of regular solutions to the initial-boundary value problem for a higher-order multidimensional system of equations of changing type with a strong nonlinear term is studied.

Key Words Equations of changing type; multidimensional system; global existence; fixed point principle.

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In domain $Q_T \equiv \{(t, x) | 0 \leq t \leq T, x = (x_1, \dots, x_n) \in \Omega \subset R^n\}$ we consider the nonlinear system of equations of changing type

$$Lu \equiv (K(t)u_t)_t + (-1)^{M-1} \sum_{|\alpha|, |\beta|=M} D_x^\alpha (A_{\alpha\beta}(x) D_x^\beta u) - \text{grad} F(u) = f(t, x) \quad (1)$$

and initial-boundary value problem

$$\begin{cases} D^\nu u = 0, & 0 \leq |\nu| \leq M - 1 \quad \text{on } \partial\Omega \times [0, T] \\ u(0, x) = \varphi(x), & x \in \Omega \subset R^n \end{cases} \quad (2)$$

where $M \geq 1$ is an integer, u, f and φ are N -dimensional vectors: $u = (u_1, \dots, u_N), f = (f_1, \dots, f_N), \varphi = (\varphi_1, \dots, \varphi_N)$; $K(t)$ is an $N \times N$ diagonal matrix: $K(t) = \text{diag} \{k_1(t), \dots, k_N(t)\}$; $A_{\alpha\beta}$ are $N \times N$ matrices; F is a nonlinear function of vector u ; Ω is a bounded domain with smooth boundary, T is any finite real number.

Assume that the coefficients and functions in (1) and (2) satisfy the following conditions:

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$$\left\{ \begin{array}{l}
\text{(i)} \quad k_i(t) > 0 \text{ when } t = 0, k_i(t) \geq 0 \text{ when } t \in (0, t_0) \\
\quad k_i(t) = 0 \text{ when } t = t_0, k_i(t) < 0 \text{ when } t \in (t_0, T] \\
\quad k_i(t) \in C^2[0, T], k_i'(t) \leq -k_0 < 0, \forall t \in [0, t_0], \quad i = 1, \dots, N \\
\text{(ii)} \quad A_{\alpha\beta}(x) \text{ are symmetric positively definite matrices :} \\
\quad \sigma_1 |D_x^M u|_{L_2(\Omega)}^2 \geq \left(\sum_{|\alpha|, |\beta|=M} A_{\alpha\beta}(x) D_x^\alpha u, D_x^\beta u \right) \geq \sigma_0 |D_x^M u|_{L_2(\Omega)}^2, \quad \sigma_0, \sigma_1 > 0 \\
\text{(iii)} \quad F \in C^2, F(\varphi(x)) \in L_1(\Omega) \text{ and } F \text{ satisfies :} \\
\quad F(u) \geq -C_1 \\
\quad \left| \frac{\partial F(u)}{\partial u_i} \right| \leq C_2 |u|^{\rho+1} + C_3, \quad i = 1, \dots, N \\
\quad \left| \frac{\partial^2 F(u)}{\partial u_i \partial u_j} \right| \leq C_4 |u|^\rho + C_5, \quad i, j = 1, \dots, N \\
\quad \text{where } C_k > 0, 1 \leq k \leq 5, \text{ and } \rho \text{ is a non-negative real number : } \rho < \frac{2}{n-1} \\
\text{(iv)} \quad \varphi_i \in H^{2M}(\Omega) \cap L_{2(\rho+1)}(\Omega), \quad f_i \in H^1(Q_T), \quad i = 1, \dots, N
\end{array} \right. \quad (3)$$

It is evident that, in the case $M = 1$, the system (1) is a nonlinear system of equations of mixed type, which is elliptic in the domain Q_{t_0} , and is hyperbolic in the domain $Q_T \setminus \overline{Q_{t_0}}$, $t = t_0$ is its degenerate plane. In the case $M > 1$, system (1) is of hypoelliptic type in Q_{t_0} , and is of ultrahyperbolic type in $Q_T \setminus \overline{Q_{t_0}}$, hence (1) is a nonlinear system of equations of changing type.

In practical problems there appear higher-order equations of changing type^[1]. There are only a few papers concerning this type of equations ([2-6]), but there is not any paper concerning the system of equations of changing type.

In the case $n = 1$ in [7] we have proved the global existence of regular solutions to the problem (1) (2) without any restriction on ρ .

In the case $n > 1$, the global existence of regular solutions to the problem (1) (2) is proved in [8] only for the case: $M = 1, 2 \leq n \leq 3, \rho \leq \frac{2}{n}$.

In this paper we solve this problem for any n and any M under the restriction $\rho < \frac{2}{n-1}$.

Assume that on the degenerate plane $t = t_0$ the following normal connected condi-