## Approximate Riemann Solvers and Robust High-Order Finite Volume Schemes for Multi-Dimensional Ideal MHD Equations

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Abstract. We design stable and high-order accurate finite volume schemes for the ideal MHD equations in multi-dimensions. We obtain excellent numerical stability due to some new elements in the algorithm. The schemes are based on three- and five-wave approximate Riemann solvers of the HLL-type, with the novelty that we allow a varying normal magnetic field. This is achieved by considering the semiconservative Godunov-Powell form of the MHD equations. We show that it is important to discretize the Godunov-Powell source term in the right way, and that the HLL-type solvers naturally provide a stable upwind discretization. Second-order versions of the ENO- and WENO-type reconstructions are proposed, together with precise modifications necessary to preserve positive pressure and density. Extending the discrete source term to second order while maintaining stability requires non-standard techniques, which we present. The first- and second-order schemes are tested on a suite of numerical experiments demonstrating impressive numerical resolution as well as stability, even on very fine meshes.

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## 1 Introduction

Many interesting problems in astrophysics, solar physics and engineering involve macroscopic plasma models and are usually described by the equations of ideal magnetohydrodynamics (MHD).

## 1.1 Derivation of the equations

In macroscopic plasma models, the variables of interest are the mass density of the plasma  $\rho$ , the velocity field  $\mathbf{u} = (u_1, u_2, u_3)^T$ , the magnetic field  $\mathbf{B} = (B_1, B_2, B_3)^T$ , the pressure p and the total energy E. The unknowns obey the following conservation (balance) laws (see [36] for details),

1. Conservation of mass: mass of a plasma is conserved, resulting in

$$\rho_t + \operatorname{div}(\rho \mathbf{u}) = 0.$$

2. Faraday's law: the magnetic flux across a surface **S** bounded by a curve  $\delta$ **S** is given by Faraday's law

$$-\frac{d}{dt}\int_{S}\mathbf{B}\cdot\mathbf{dS} = \int_{\delta S} E\cdot dl.$$

By using Stokes Theorem and the fact that the electric field in a co-moving frame is zero and assuming zero resistivity, Faraday's law leads to

$$\mathbf{B}_t + \operatorname{curl}(\mathbf{B} \times \mathbf{u}) = -\mathbf{u}(\operatorname{div} \mathbf{B}). \tag{1.1}$$

The above equation is termed the magnetic induction equation and can also be written in the divergence form

$$\mathbf{B}_t + \operatorname{div}(\mathbf{u} \otimes \mathbf{B} - \mathbf{B} \otimes \mathbf{u}) = -\mathbf{u}(\operatorname{div} \mathbf{B}).$$

3. Conservation of momentum: in differential form, the conservation of momentum is

$$(\rho \mathbf{u})_t + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + p\mathcal{I}) = \mathbf{J} \times \mathbf{B},$$

where **J** denotes the current density and  $\mathcal{I}$  the 3×3 identity matrix. The Lorentz force exerted by the magnetic field is given by **J**×**B**. Under the assumptions of ideal MHD, Ampere's law expresses the current density as

$$\mathbf{J} = \operatorname{curl}(\mathbf{B}).$$

Using standard vector identities results in the following semi-conservative form,

$$(\rho \mathbf{u})_t + \operatorname{div}\left(\rho \mathbf{u} \otimes \mathbf{u} + \left(p + \frac{1}{2}\mathbf{B}^2\right)\mathcal{I} - \mathbf{B} \otimes \mathbf{B}\right) = -\mathbf{B}(\operatorname{div}\mathbf{B}).$$